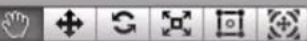


IATK: Immersive Analytics Toolkit

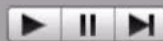
An Introduction - ARIVE



Dr. Maxime Cordeil
Lecturer, Immersive Analytics Group, Monash FIT



Pivot Global



Collab



Account

Layers

Layout

Hierarchy

Create All

Untitled*

Main Camera
Directional Light
[IATK] New Data Source
[IATK] New Visualisation
Key(Clone)

Scene

Asset Store

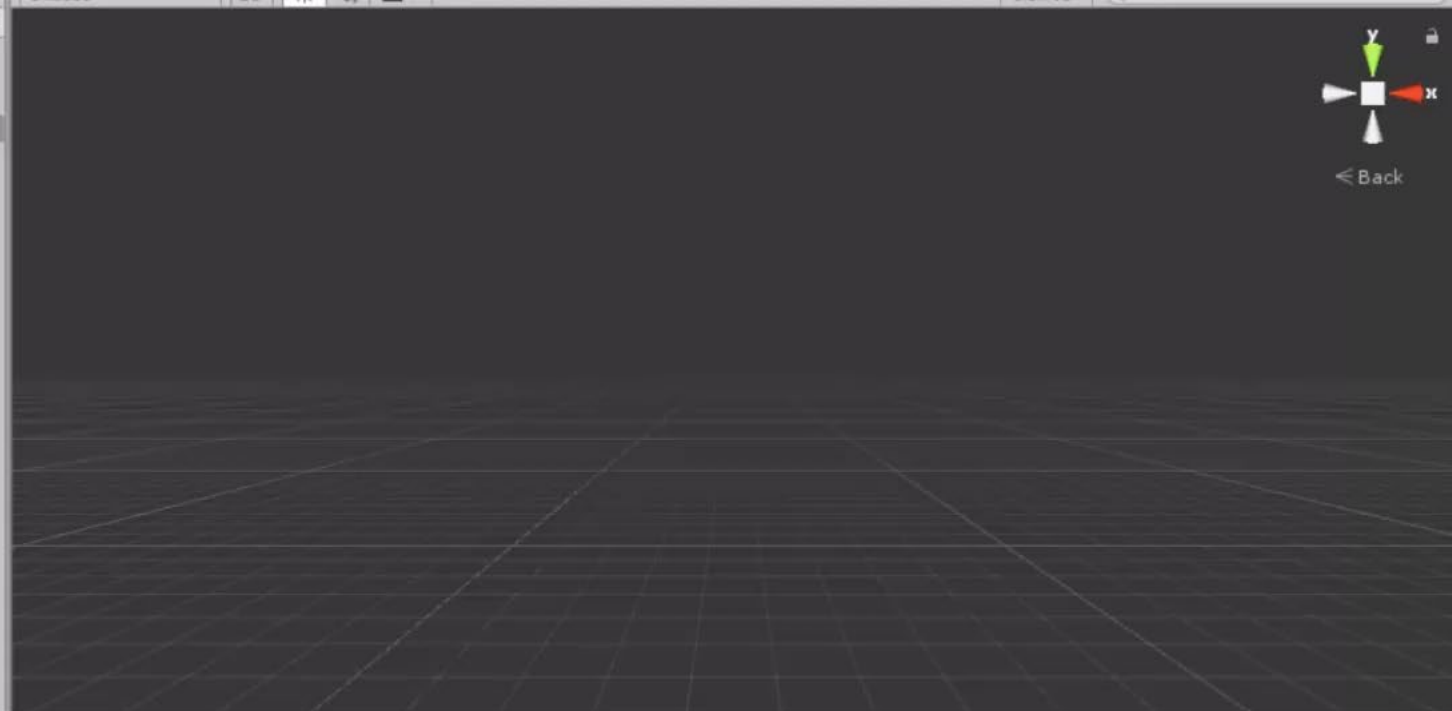
Shaded

2D



Gizmos

All



Inspector

[IATK] New Visualisation

Static

Tag

Untagged

Layer

Default

Transform

Position X 0 Y 0 Z 0
Rotation X 0 Y 0 Z 0
Scale X 1 Y 1 Z 1

Visualisation (Script)

Uid 84899932

Data Source [IATK] New Data

Visualisation Type SCATTERPLOT

Undefined

Undefined

Undefined

X_AXIS

Undefined

Undefined

Y_AXIS

Undefined

Undefined

Z_AXIS

Undefined

Undefined

Geometry Undefined

Colour dimension Undefined

Bind Colour palette Undefined

Blending Mode Source SrcAlpha

Blending Mode Destination OneMinusSrcAlpha

Colour

Size dimension Undefined

Linking dimension Undefined

Attribute Filters

Size 0

Size 0.3

Min Size 0.01

Max Size 1

Width 1

Height 1

Depth 1

Project

Console

Create

All Materials
All Models
All Prefabs

Assets

Datasets

IATK

Editor
Materials
Meshes
Prefabs
Resources
Scenes_Tutorial
Scripts
Controller

Assets Datasets

GPSTRACKS
International_airline_activity_Table1_2004to2008_web
International_airline_activity_Table1_2004to2008_web
qlh3b32q
results_0_pilot_final_arnaud_log
SetOfStacks
test
transform
Uber-Jan-Feb-FOIL
uber-raw-data-jun14
Victoria_flights 1
WineQualityCombined

Immersive Analytics: FIT & externals



Tim Dwyer



Kim Marriott



Bernie Jenny



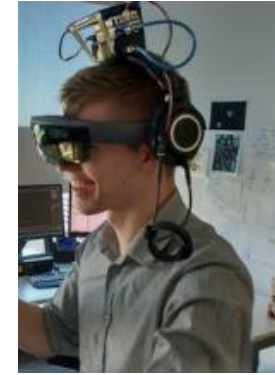
Sarah Goodwin



Maxime Cordeil



Tobias Czauderna



Peter Hoghton



Domenico Mazza



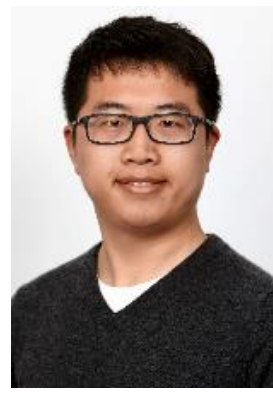
Arnaud Prouzeau



Barrett Ens



Matthias
Klapperstueck



Yalong Yang



Benjamin Bach



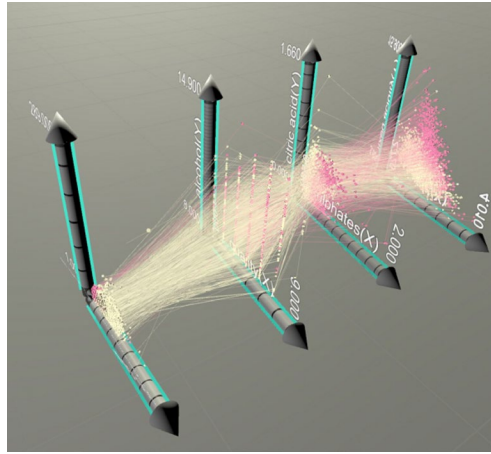
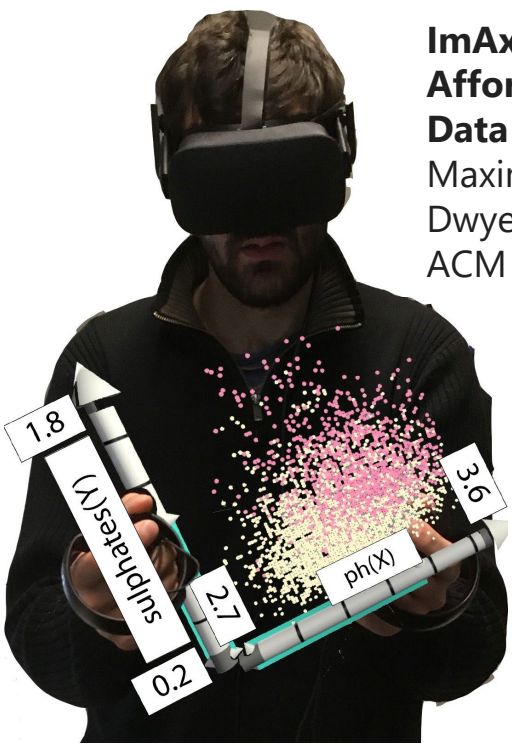
Bruce Thomas
UniSA



Andrew Cunningham
UniSA

ImAxes: Immersive Axes as Embodied Affordances for Interactive Multivariate Data Visualisation

Maxime Cordeil, Andrew Cunningham, Tim Dwyer, Bruce H. Thomas and Kim Marriott
ACM UIST 2017



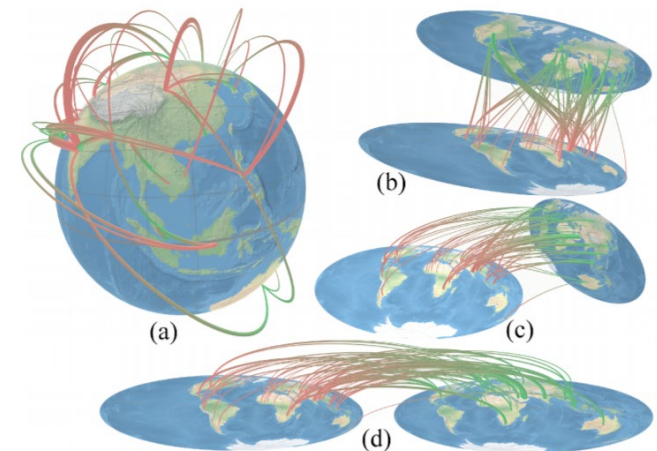
FibreClay – Immersive 3D curves exploration

Hurter, Riche, Drucker, Cordeil, Alligier, Vuillemot
IEEE InfoVis (TVCG) 19



Origin-Destination Flow Maps in Immersive Environments

Yalong Yang, Tim Dwyer, Bernhard Jenny, Kim Marriott, Maxime Cordeil and Haohui Chen



IEEE VIS, InfoVis/TVCG 18



Maps Around Me: 3D Multiview Layouts in Immersive Spaces

Satriadi, Ens, Cordeil, Czauderna, Jenny
ACM ISS 2020, to appear

ImAxes: Immersive Axes as Embodied Affordances for Interactive Multivariate Data Visualisation

Maxime Cordeil
Andrew Cunningham
Tim Dwyer
Bruce H. Thomas
Kim Marriott

UIST 2017

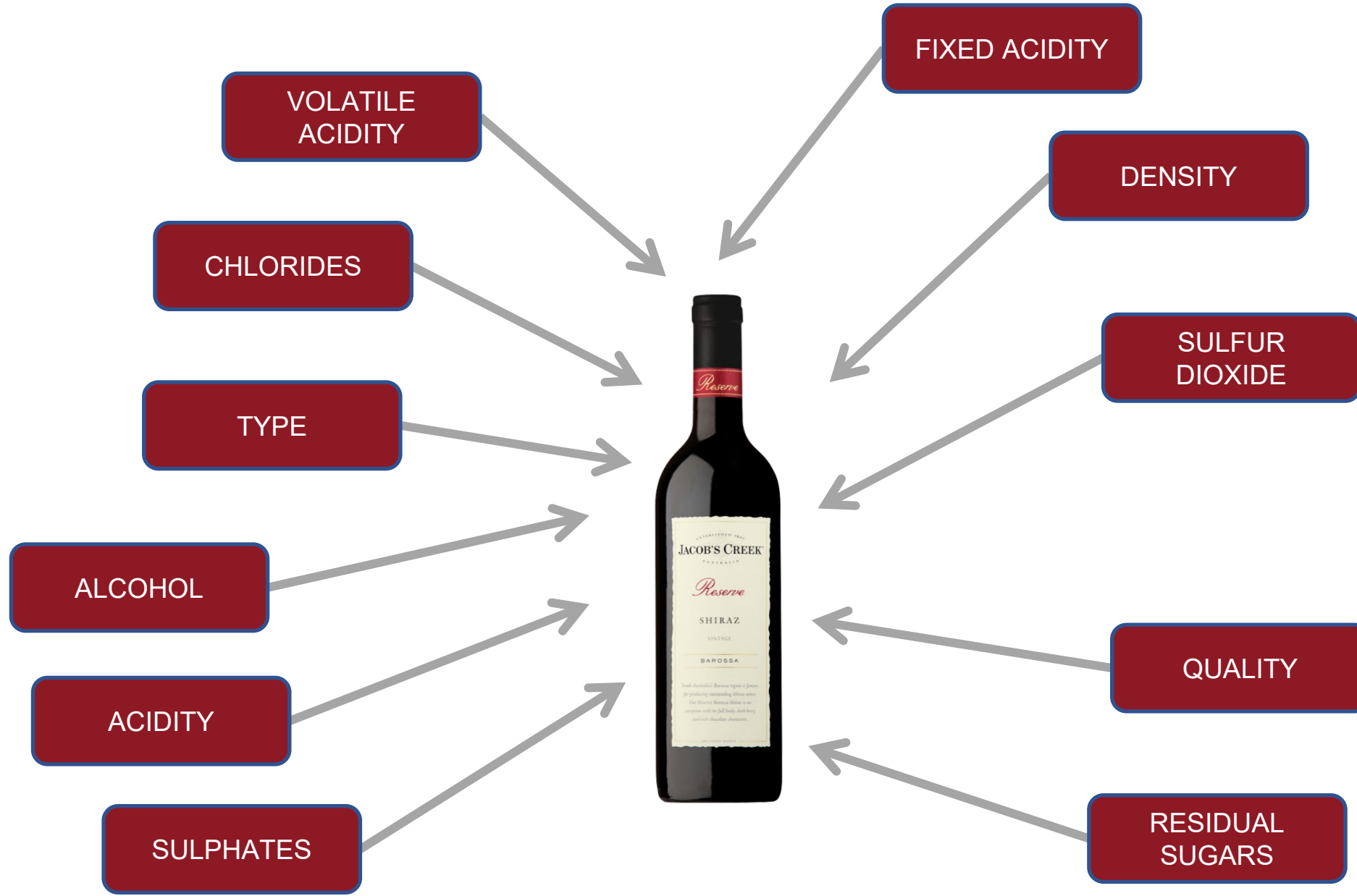


MONASH
University

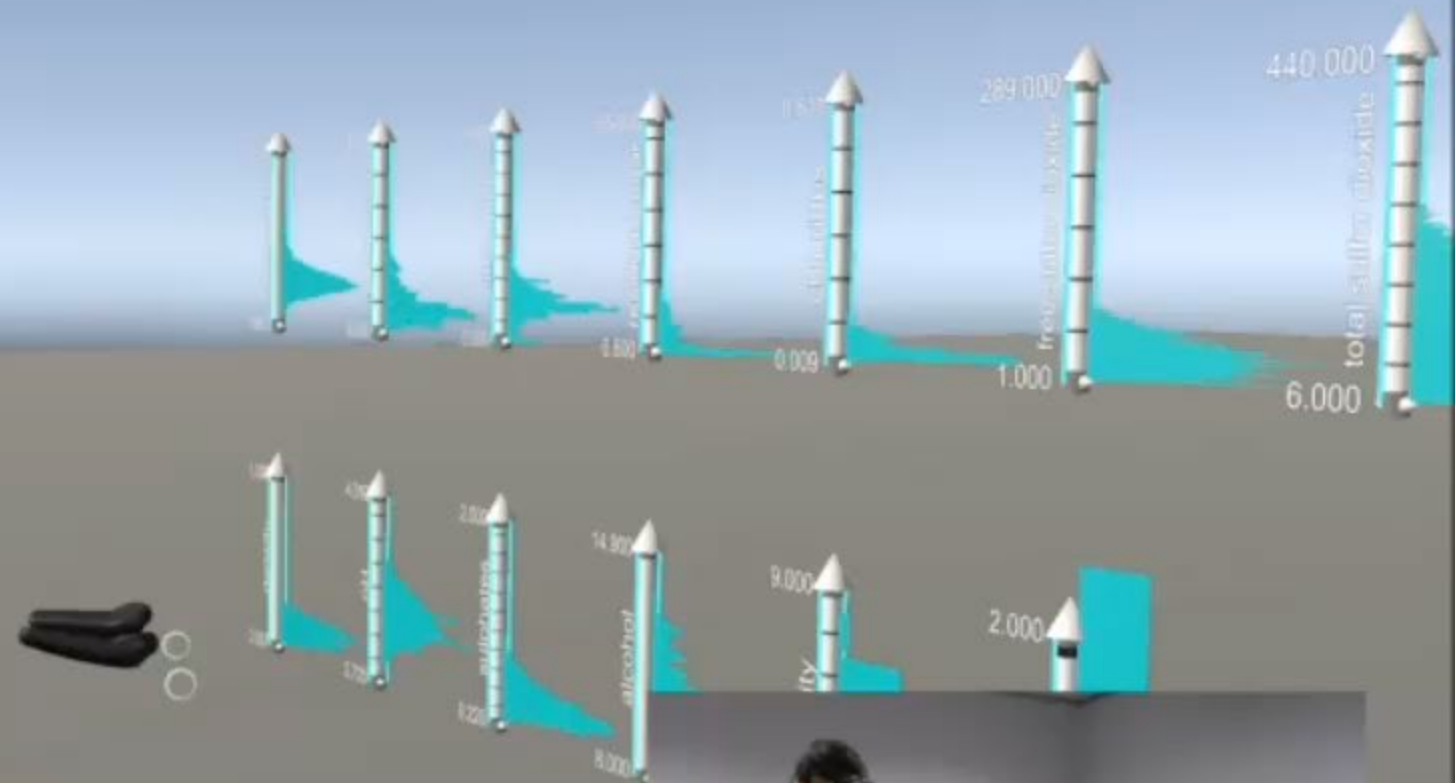


University of
South Australia

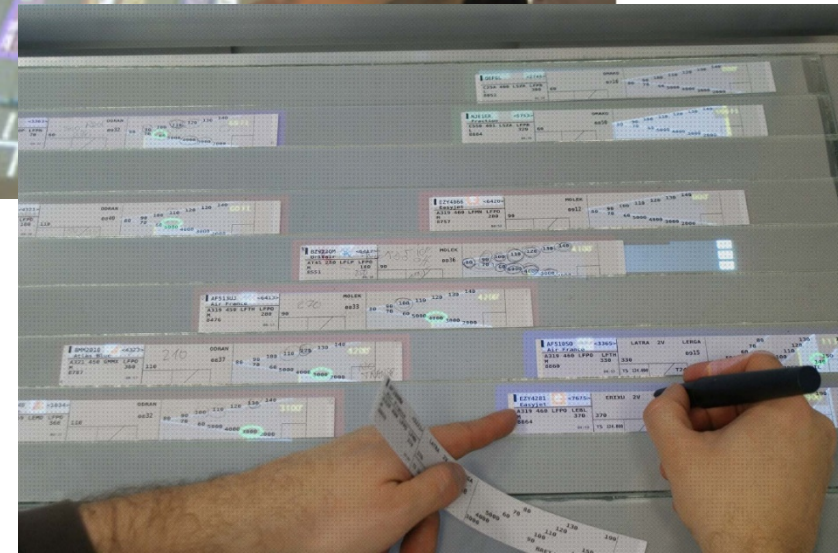
Multidimensional data



	A	B	C	D	E	F	G	H	I	J	K	L	M
1	fixed acidity	volatile acidity	citric acid	residual sugar	chlorides	free sulfur dioxide	total sulfur dioxide	density	pH	sulphates	alcohol	quality	Type
2	7	0.27	0.36	20.7	0.045	45	170	1.001	3	0.45	8.8	6	White
3	6.3	0.3	0.34	1.6	0.049	14	132	0.994	3.3	0.49	9.5	6	White
4	8.1	0.28	0.4	6.9	0.05	30	97	0.9951	3.26	0.44	10.1	6	White
5	7.2	0.23	0.32	8.5	0.058	47	186	0.9956	3.19	0.4	9.9	6	White
6	7.2	0.23	0.32	8.5	0.058	47	186	0.9956	3.19	0.4	9.9	6	White
7	8.1	0.28	0.4	6.9	0.05	30	97	0.9951	3.26	0.44	10.1	6	White
8	6.2	0.32	0.16	7	0.045	30	136	0.9949	3.18	0.47	9.6	6	White
9	7	0.27	0.36	20.7	0.045	45	170	1.001	3	0.45	8.8	6	White
10	6.3	0.3	0.34	1.6	0.049	14	132	0.994	3.3	0.49	9.5	6	White
11	8.1	0.22	0.43	1.5	0.044	28	129	0.9938	3.22	0.45	11	6	White
12	8.1	0.27	0.41	1.45	0.033	11	63	0.9908	2.99	0.56	12	5	White
13	8.6	0.23	0.4	4.2	0.035	17	109	0.9947	3.14	0.53	9.7	5	White
14	7.9	0.18	0.37	1.2	0.04	16	75	0.992	3.18	0.63	10.8	5	White
15	6.6	0.16	0.4	1.5	0.044	48	143	0.9912	3.54	0.52	12.4	7	White
16	8.3	0.42	0.62	19.25	0.04	41	172	1.0002	2.98	0.67	9.7	5	White
17	6.6	0.17	0.38	1.5	0.032	28	112	0.9914	3.25	0.55	11.4	7	White
18	6.3	0.48	0.04	1.1	0.046	30	99	0.9928	3.24	0.36	9.6	6	White
19	6.2	0.66	0.48	1.2	0.029	29	75	0.9892	3.33	0.39	12.8	8	White
20	7.4	0.34	0.42	1.1	0.033	17	171	0.9917	3.12	0.53	11.3	6	White
21	6.5	0.31	0.14	7.5	0.044	34	133	0.9955	3.22	0.5	9.5	5	White
22	6.2	0.66	0.48	1.2	0.029	29	75	0.9892	3.33	0.39	12.8	8	White
23	6.4	0.31	0.38	2.9	0.038	19	102	0.9912	3.17	0.35	11	7	White
24	6.8	0.26	0.42	1.7	0.049	41	122	0.993	3.47	0.48	10.5	8	White
25	7.6	0.67	0.14	1.5	0.074	25	168	0.9937	3.05	0.51	9.3	5	White
26	6.6	0.27	0.41	1.3	0.052	16	142	0.9951	3.42	0.47	10	6	White
27	7	0.25	0.32	9	0.046	56	245	0.9955	3.25	0.5	10.4	6	White
28	6.9	0.24	0.35	1	0.052	35	146	0.993	3.45	0.44	10	6	White
29	7	0.28	0.39	8.7	0.051	32	141	0.9961	3.38	0.53	10.5	6	White
30	7.4	0.27	0.48	1.1	0.047	17	132	0.9914	3.19	0.49	11.6	6	White
31	7.2	0.32	0.36	2	0.033	37	114	0.9906	3.1	0.71	12.3	7	White
32	8.5	0.24	0.39	10.4	0.044	20	142	0.9974	3.2	0.53	10	6	White
33	8.3	0.14	0.34	1.1	0.042	7	47	0.9934	3.47	0.4	10.2	6	White
34	7.4	0.25	0.36	2.05	0.05	31	100	0.992	3.19	0.44	10.8	6	White
35	6.2	0.12	0.34	1.5	0.045	43	117	0.9939	3.42	0.51	9	6	White
36	5.8	0.27	0.2	14.95	0.044	22	179	0.9962	3.37	0.37	10.2	5	White
37	7.3	0.28	0.43	1.7	0.08	21	123	0.9905	3.19	0.42	12.8	5	White
38	6.5	0.39	0.23	5.4	0.051	25	149	0.9934	3.24	0.35	10	5	White
39	7	0.33	0.32	1.2	0.053	38	138	0.9906	3.13	0.28	11.2	6	White
40	7.3	0.24	0.39	17.95	0.057	45	149	0.9999	3.21	0.36	8.6	5	White
41	7.3	0.24	0.39	17.95	0.057	45	149	0.9999	3.21	0.36	8.6	5	White
42	6.7	0.23	0.39	2.5	0.172	63	158	0.9937	3.11	0.36	9.4	6	White
43	6.7	0.24	0.39	2.9	0.173	63	157	0.9937	3.1	0.34	9.4	6	White
44	7	0.31	0.26	7.4	0.069	28	160	0.9954	3.13	0.46	9.8	6	White
45	6.6	0.24	0.27	1.4	0.057	33	152	0.9934	3.22	0.56	9.5	6	White
46	6.7	0.23	0.26	1.4	0.06	33	154	0.9934	3.24	0.56	9.5	6	White
47	7.4	0.18	0.31	1.4	0.058	38	167	0.9931	3.16	0.53	10	7	White
48	6.2	0.45	0.26	4.4	0.063	63	206	0.994	3.27	0.52	9.8	4	White
49	6.2	0.46	0.25	4.4	0.066	62	207	0.9939	3.25	0.52	9.8	5	White
50	7	0.31	0.26	7.4	0.069	28	160	0.9954	3.13	0.46	9.8	6	White
51	6.9	0.19	0.35	5	0.067	32	150	0.995	3.36	0.48	9.8	5	White
52	7.2	0.19	0.31	1.6	0.062	31	173	0.9917	3.35	0.44	11.7	6	White
53	6.6	0.25	0.29	1.1	0.068	39	124	0.9914	3.34	0.58	11	7	White
54	6.2	0.16	0.33	1.1	0.057	21	82	0.991	3.32	0.46	10.9	7	White
55	6.4	0.18	0.35	1	0.045	39	108	0.9911	3.31	0.35	10.9	6	White
56	6.8	0.2	0.59	0.9	0.147	38	132	0.993	3.05	0.38	9.1	6	White
57	6.9	0.25	0.35	1.3	0.039	29	191	0.9908	3.13	0.52	11	6	White
58	7.2	0.21	0.34	11.9	0.043	37	213	0.9962	3.09	0.5	9.6	6	White
59	6	0.19	0.26	12.4	0.048	50	147	0.9972	3.3	0.36	8.9	6	White



Axes as embodied* affordances**



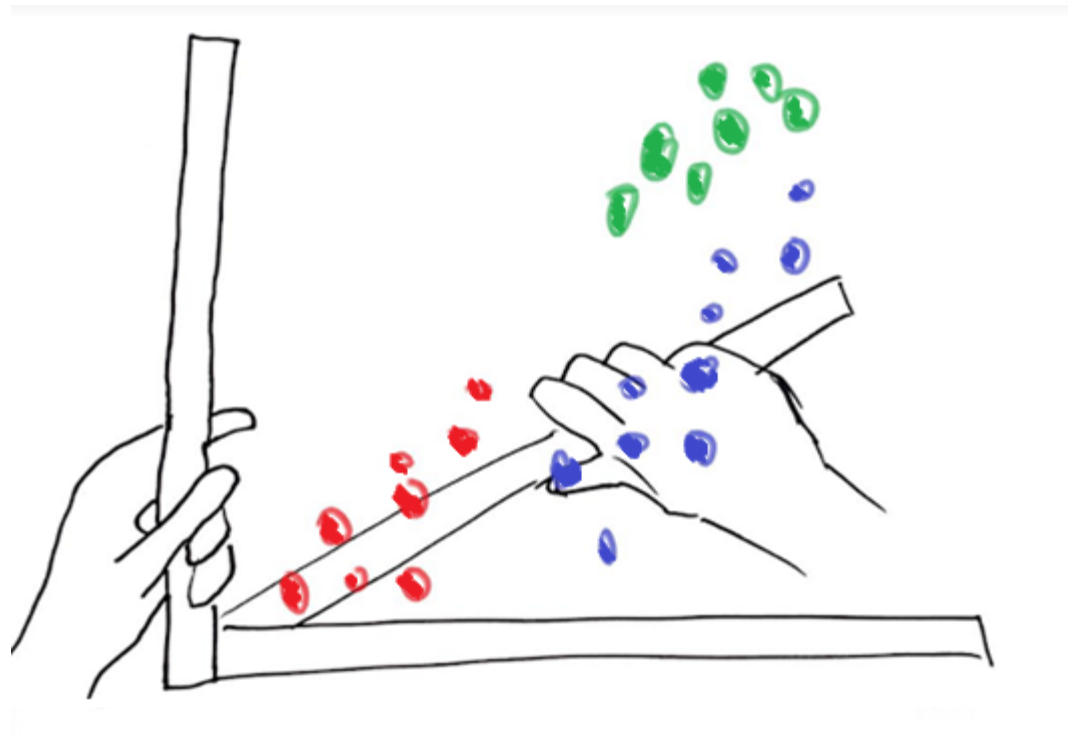
* Dourish, P. (2004)
** DA Norman (2002)

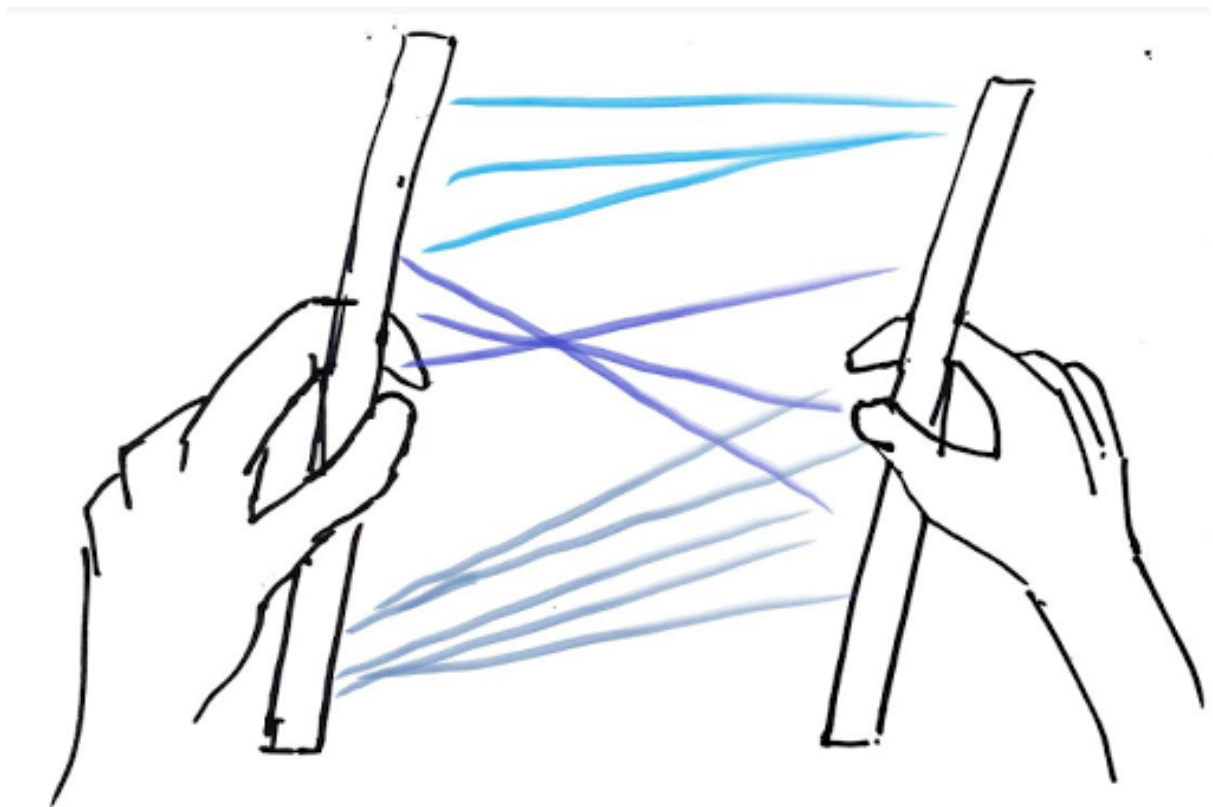
Axes as embodied* affordances**

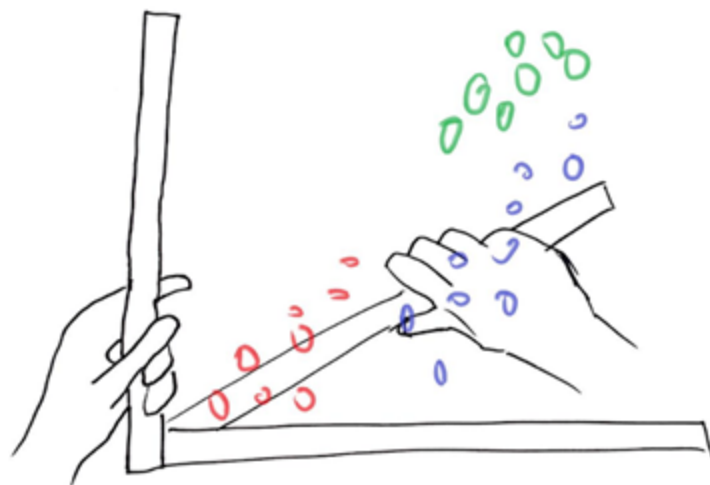
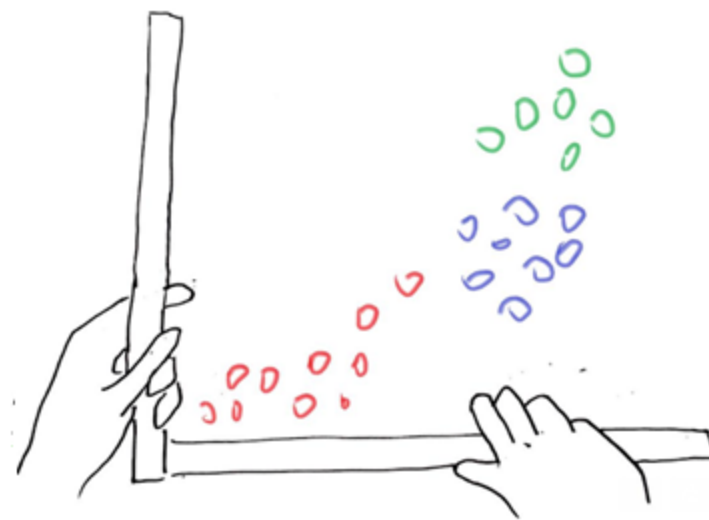
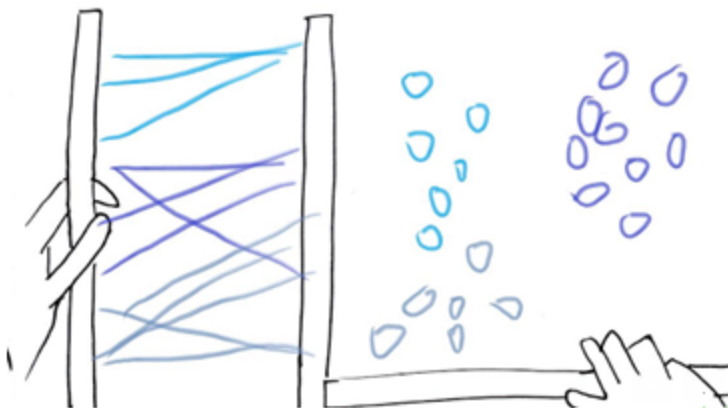
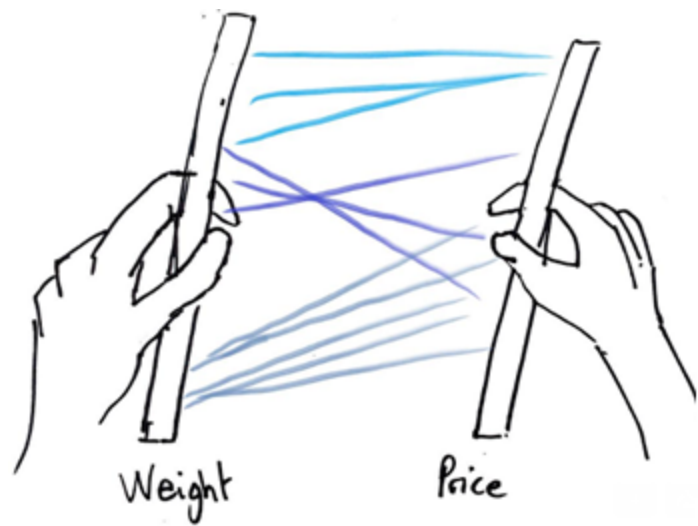


* Dourish, P. (2004)
** DA Norman (2002)

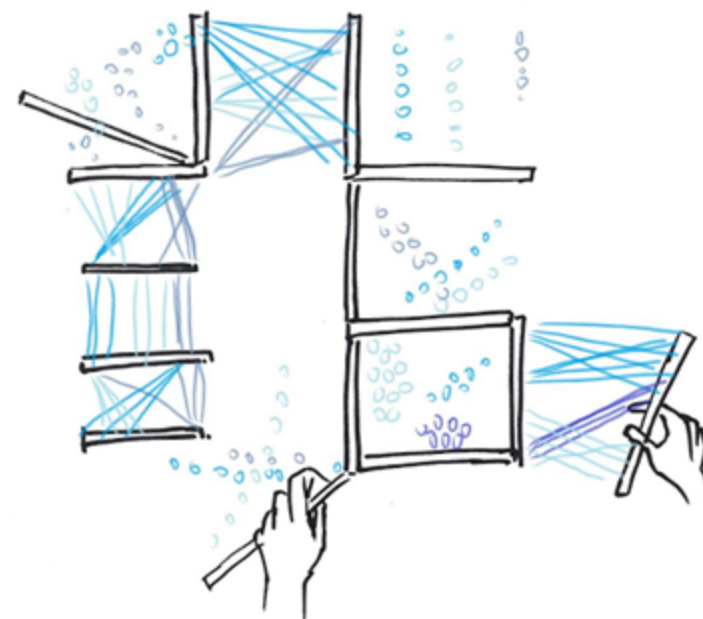
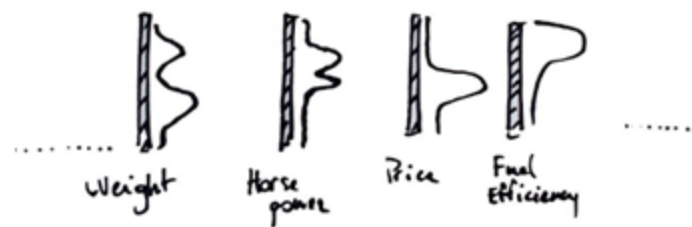
ImAxes design



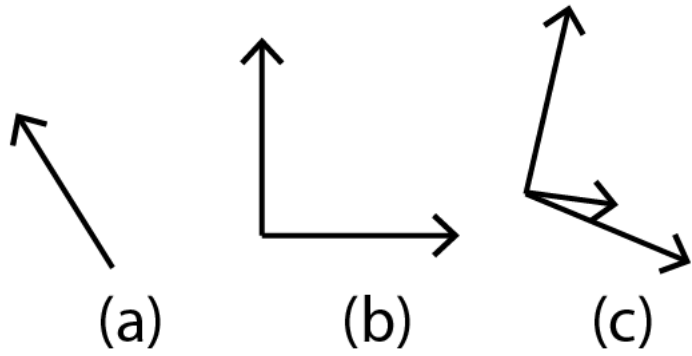




DIMENSION AXES:

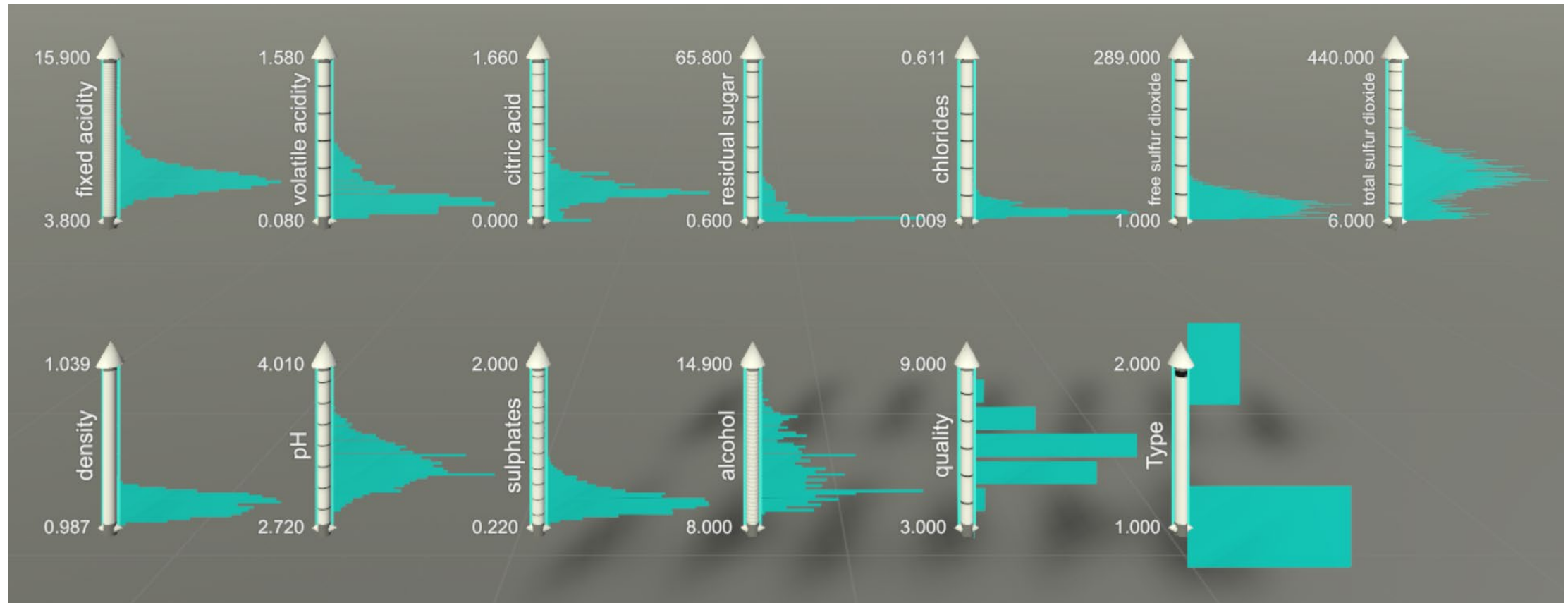


spatial grammar

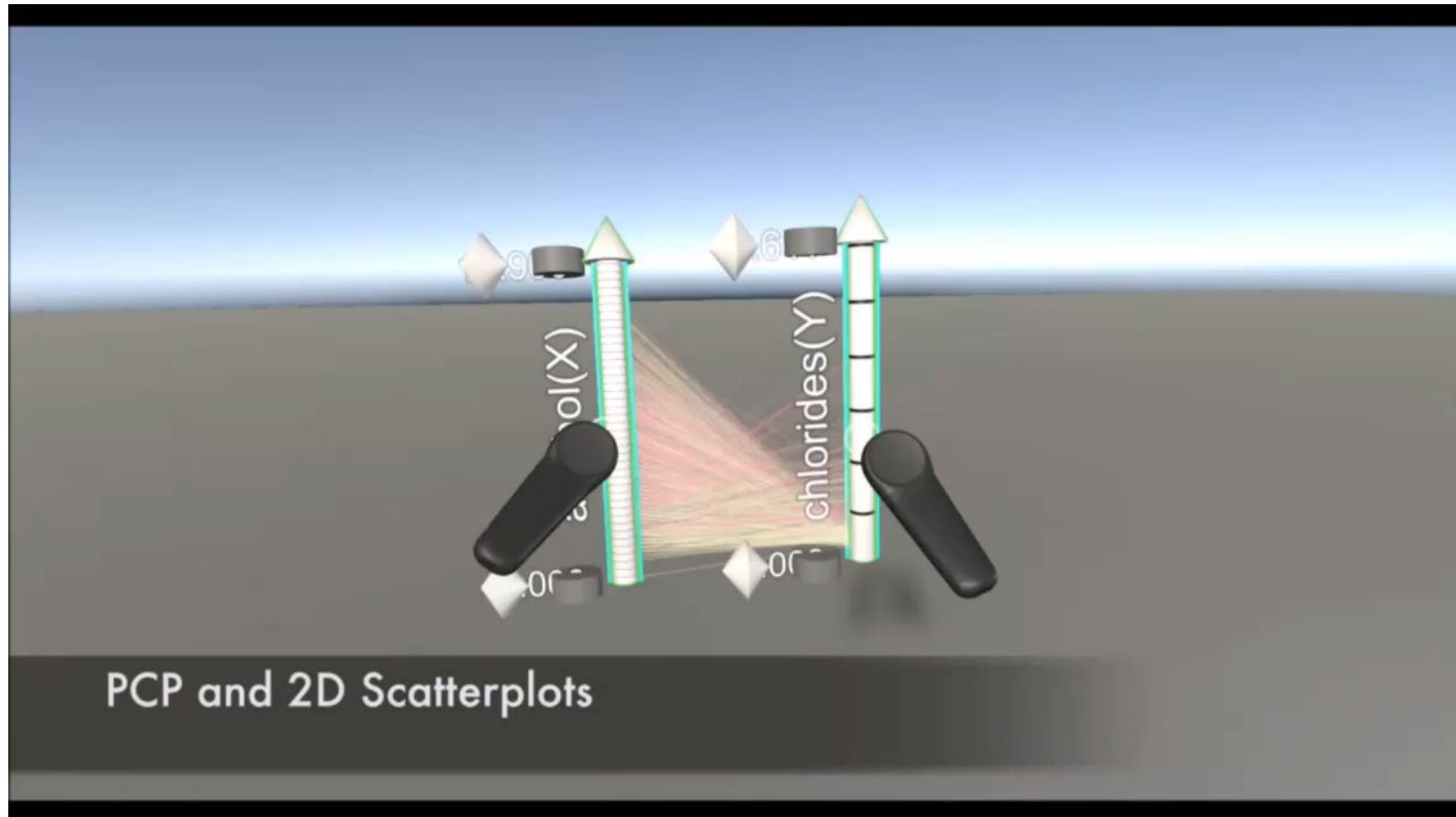


- direction, orthogonal, parallel, contact
- S_1, S_2, S_3

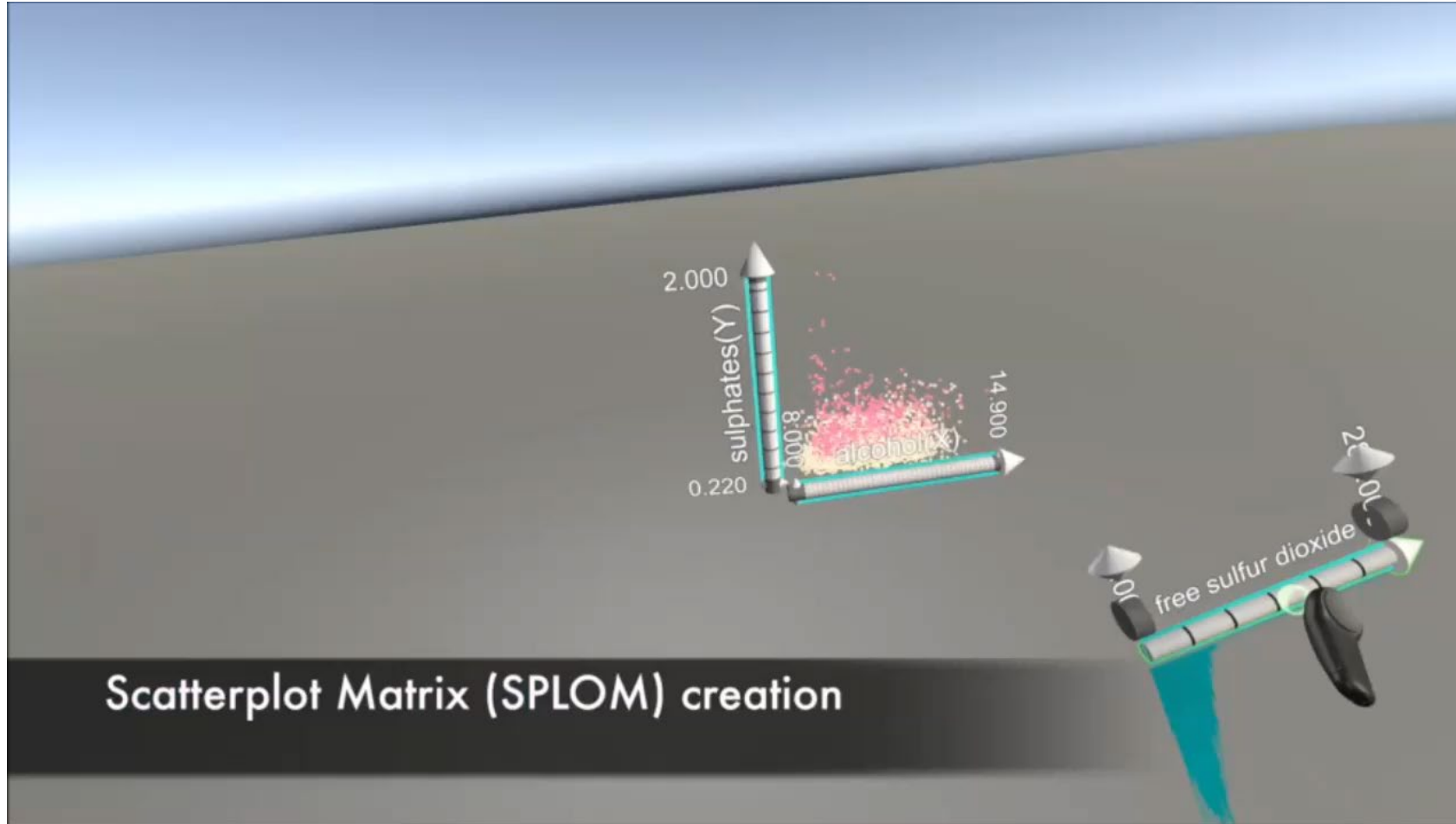
$$S_1(\text{dir}(s, e), \{\text{axis}(s, e, d)\}) \quad \leftarrow \quad \text{axis}(s, e, d)$$



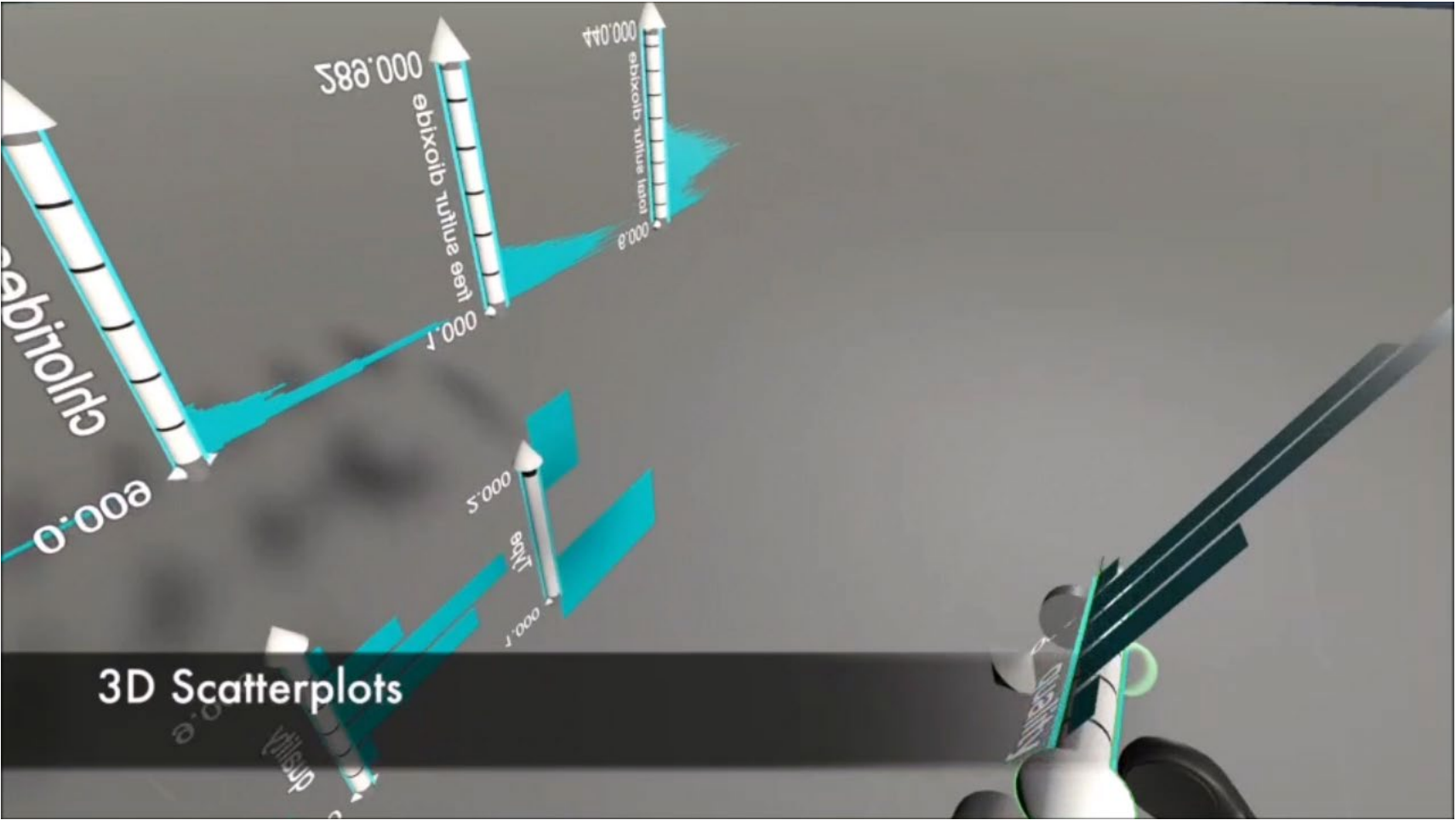
$$S_2(\vec{v}_1, \vec{v}_2, A_1, \{a\}) \quad \leftarrow \quad S_I(v_1, A_1), S_I(\vec{v}_2, \{a\}) \quad \perp(\{\vec{v}_1, \vec{v}_2\}) \wedge \otimes(A_1, \{a\})$$

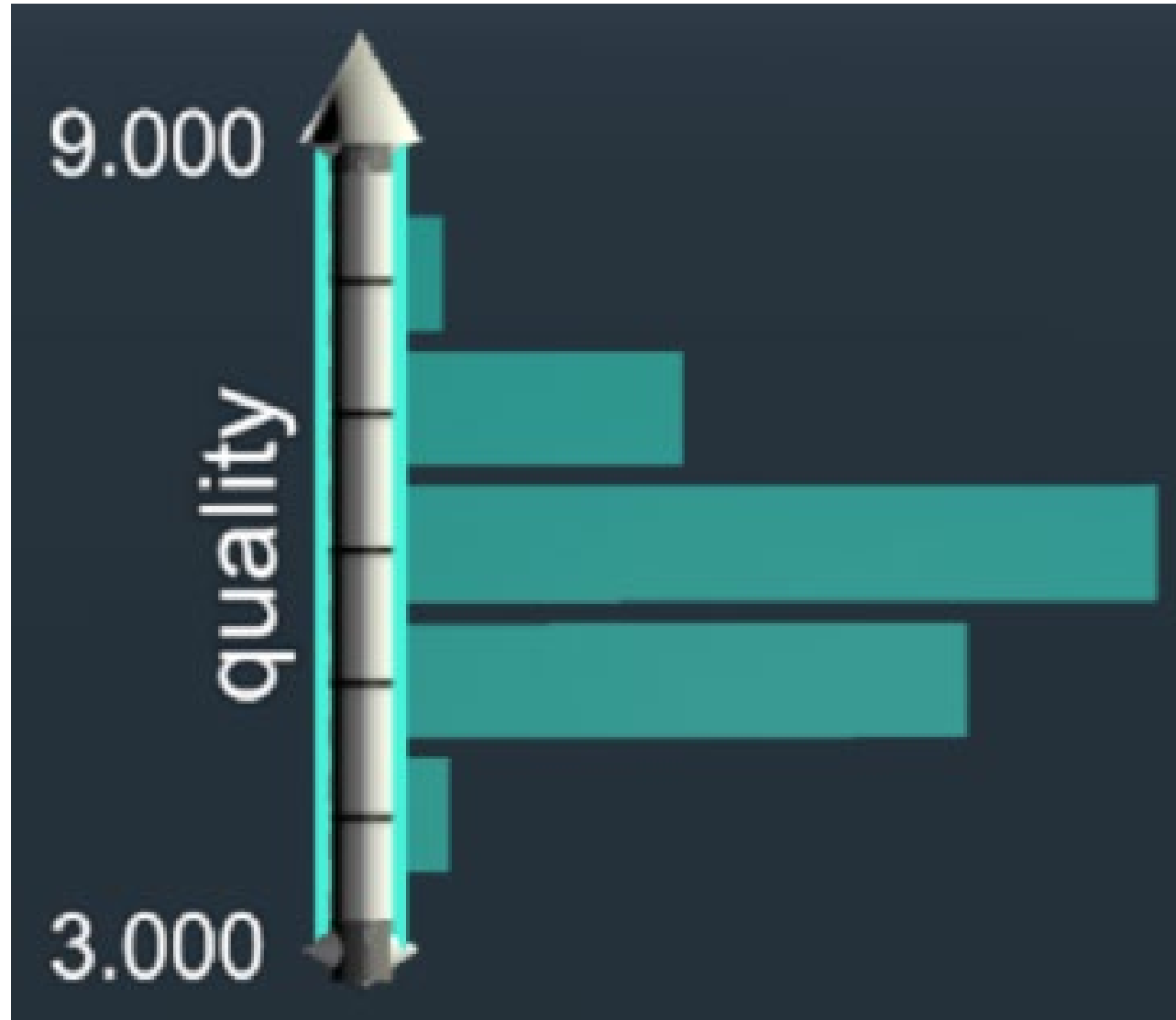


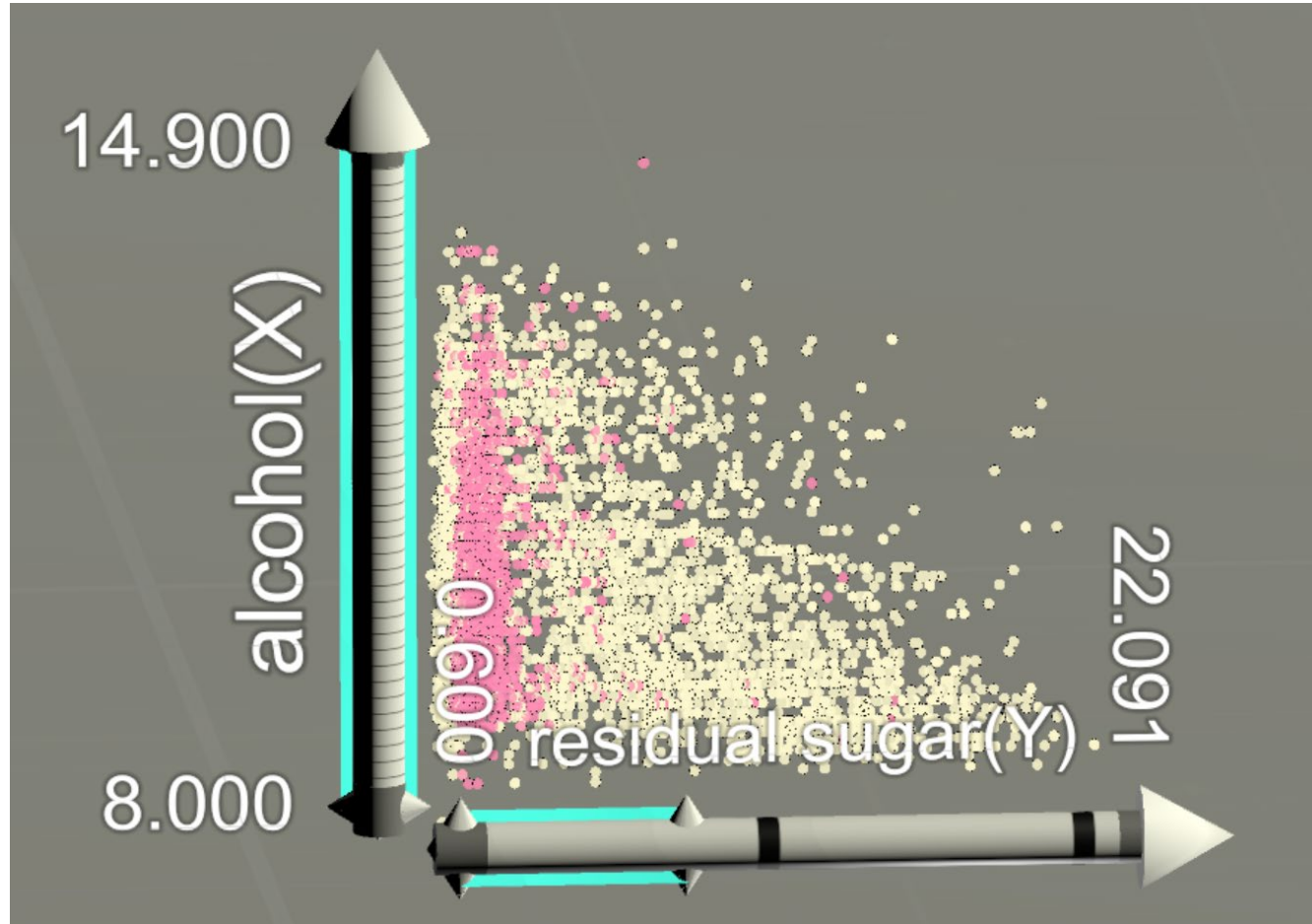
$$S_2(v_1, v_2, A_1, A_2 \cup \{a\}) \leftarrow S_2(\vec{v}_1, \vec{v}_2, A_1, A_2), S_1(v, \{a\}) \parallel (\vec{v}_2, \vec{v}) \wedge \otimes(A_1, A_2 \cup \{a\})$$

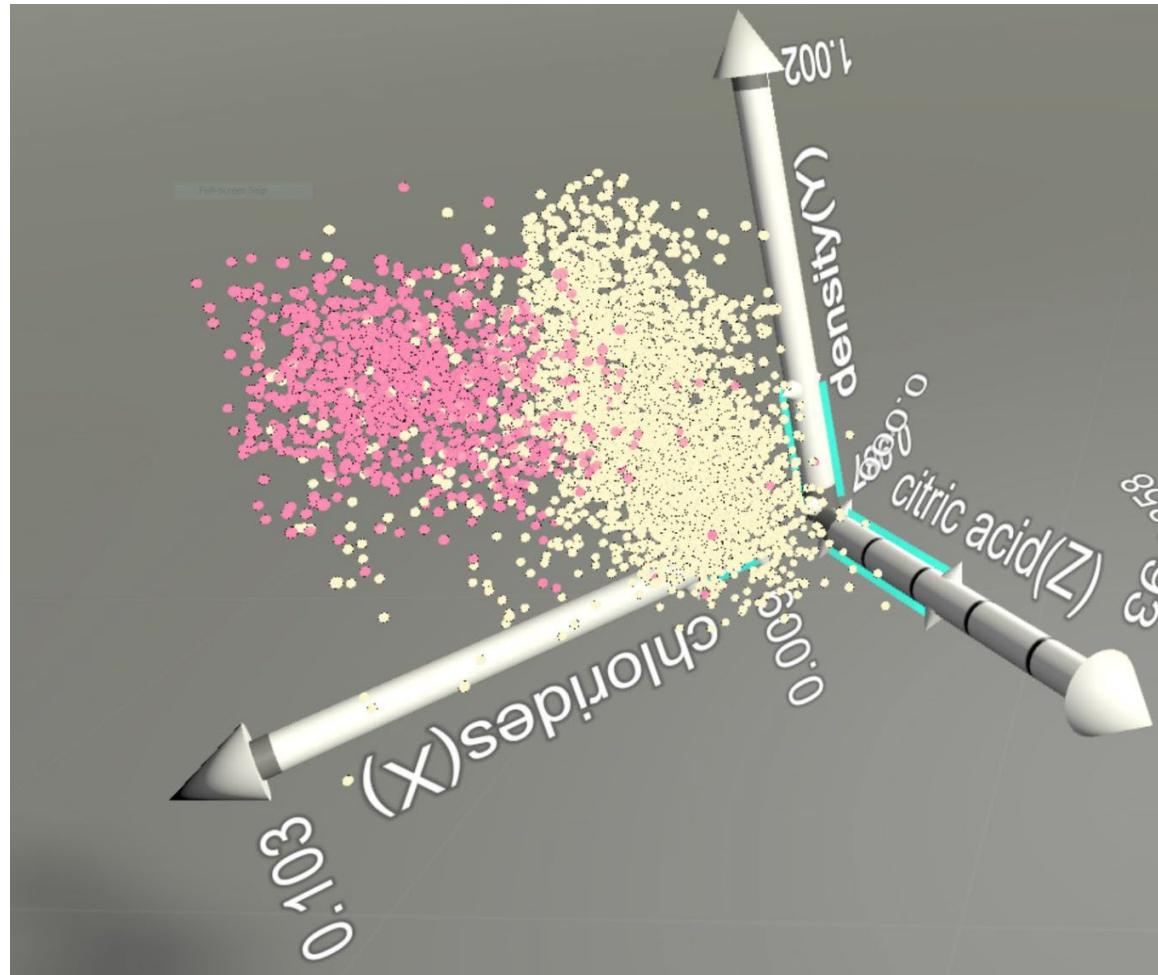


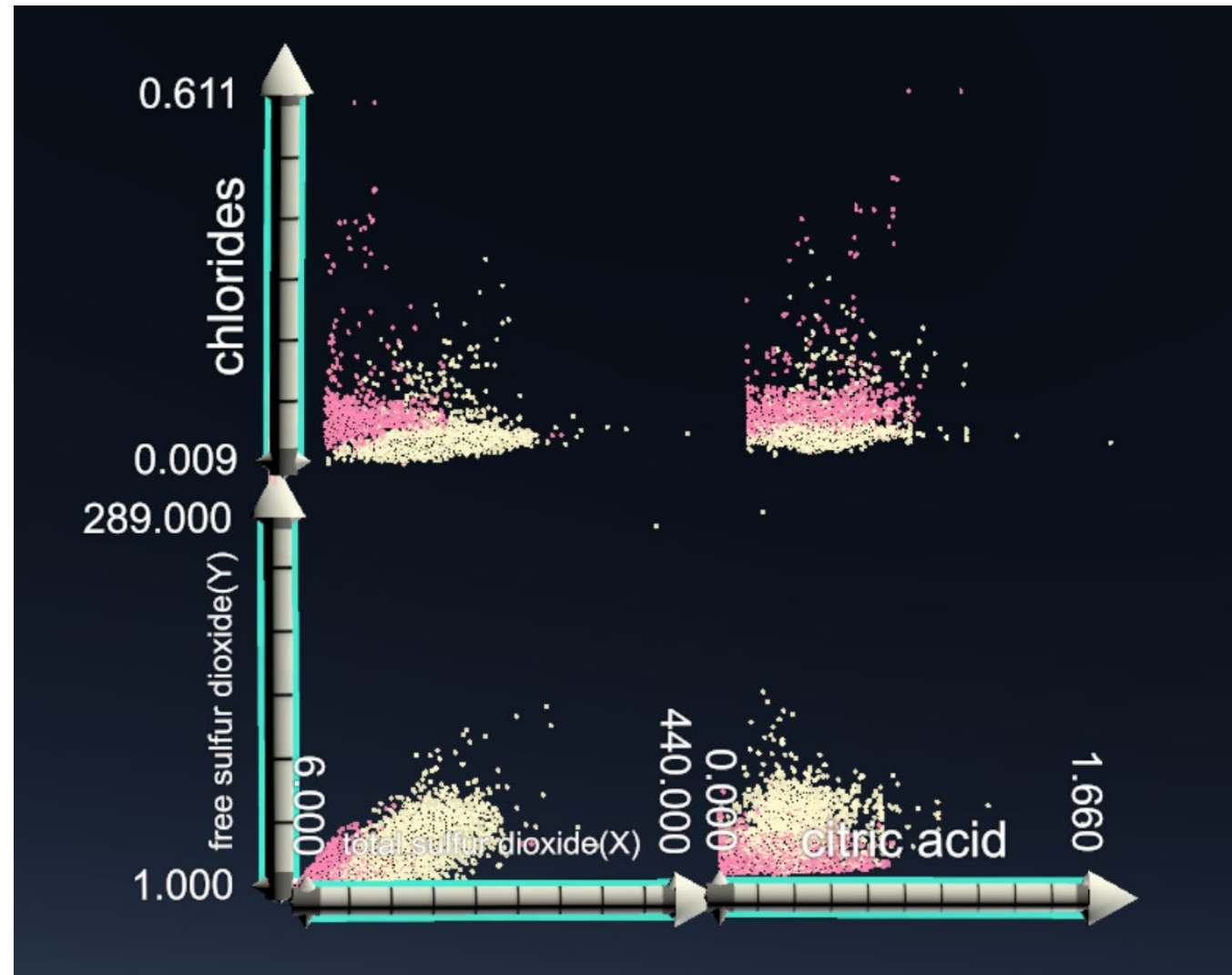
$$S_3(\vec{v}_1, \vec{v}_2, \vec{v}_3, A_1, A_2, \{a\}) \leftarrow S_2(\vec{v}_1, \vec{v}_2, A_1, A_2), S_1(\vec{v}_3, \{a\}) \perp (\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}) \wedge \otimes (A_1, A_2, A_3 \cup \{a\})$$

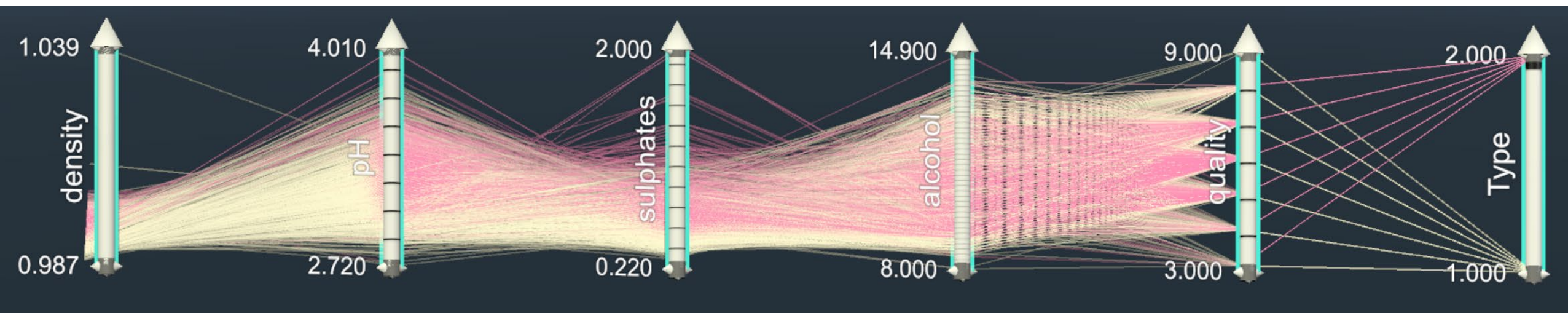


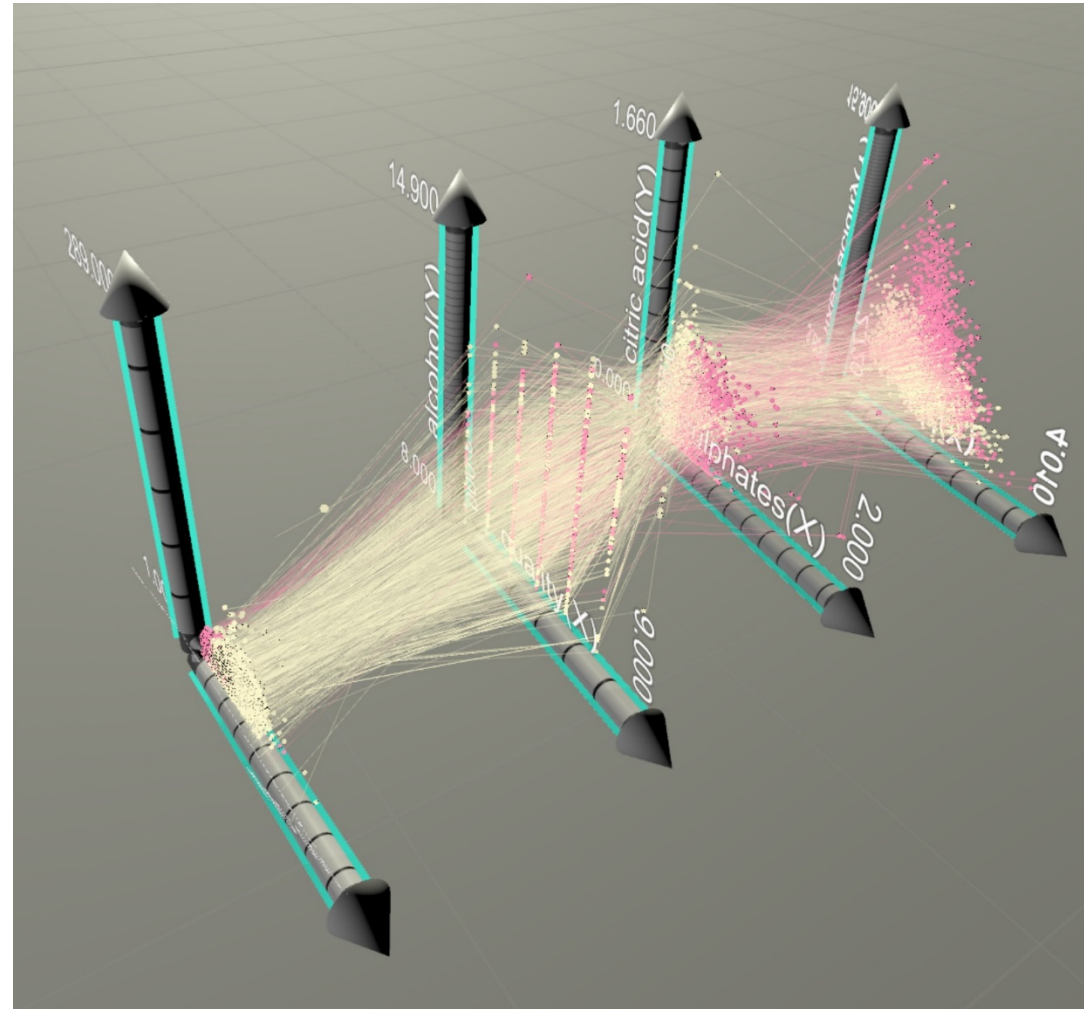




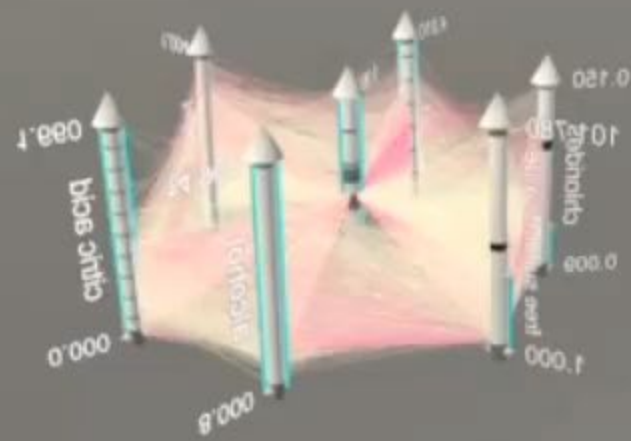






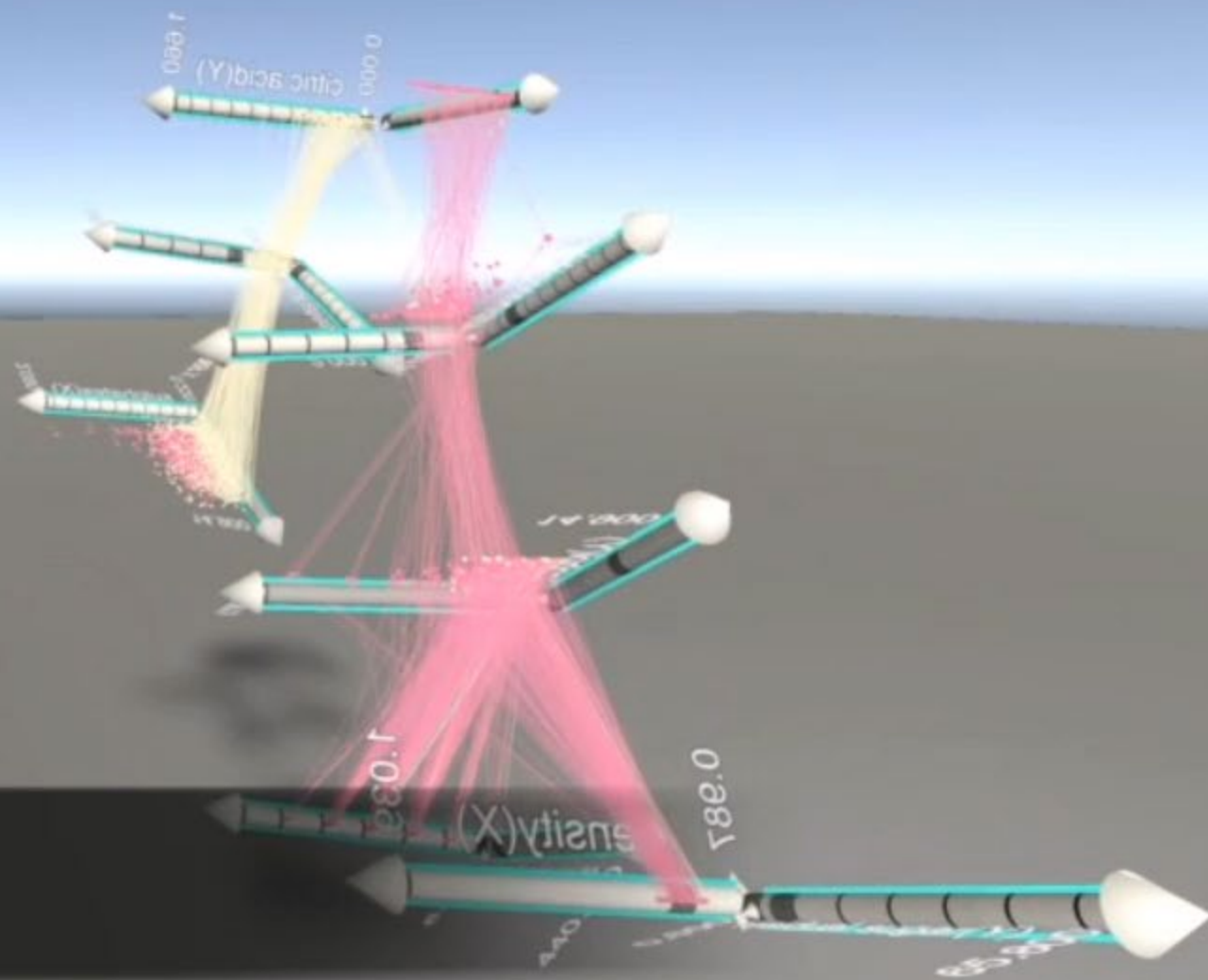


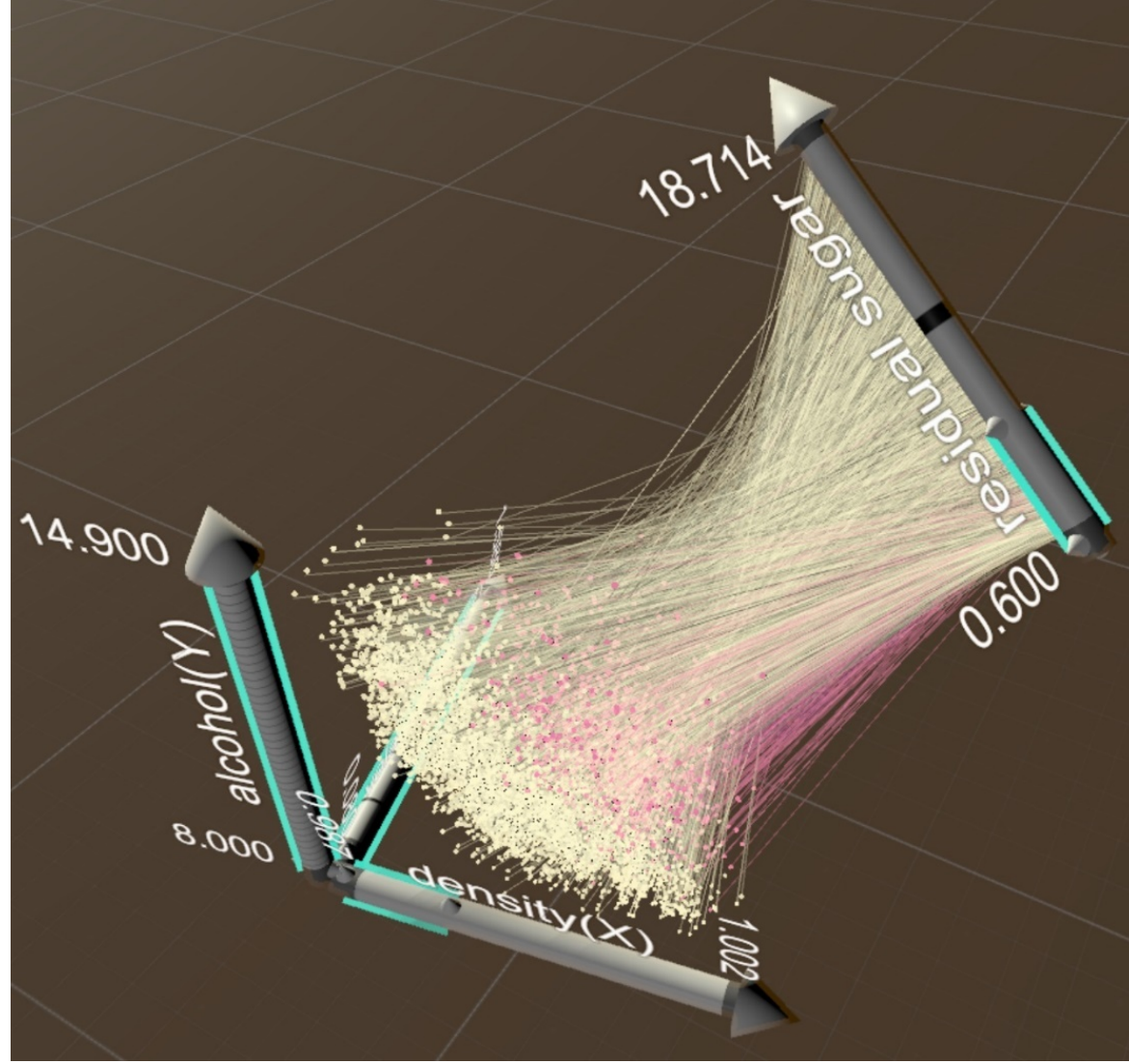
emerging visualisations

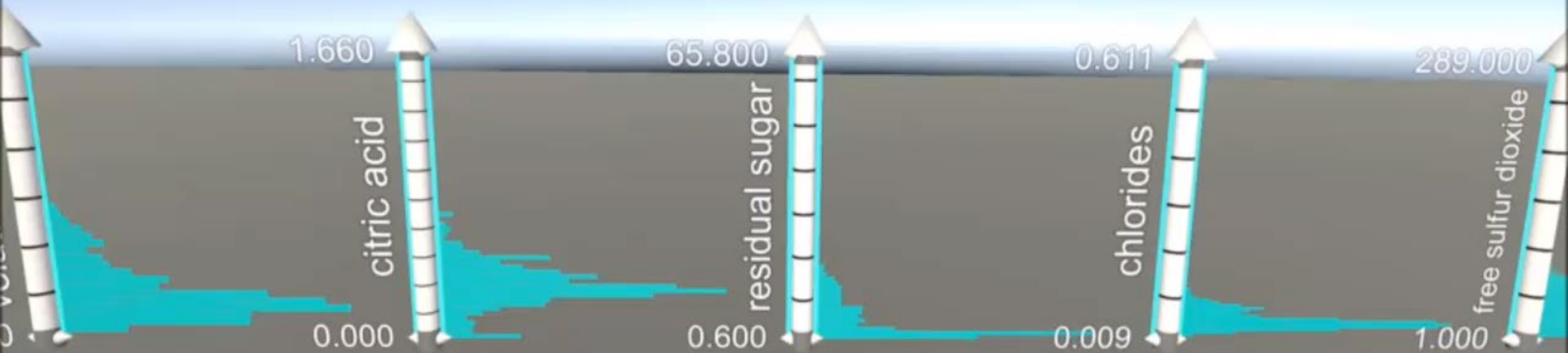


3D Circular connected PCPs

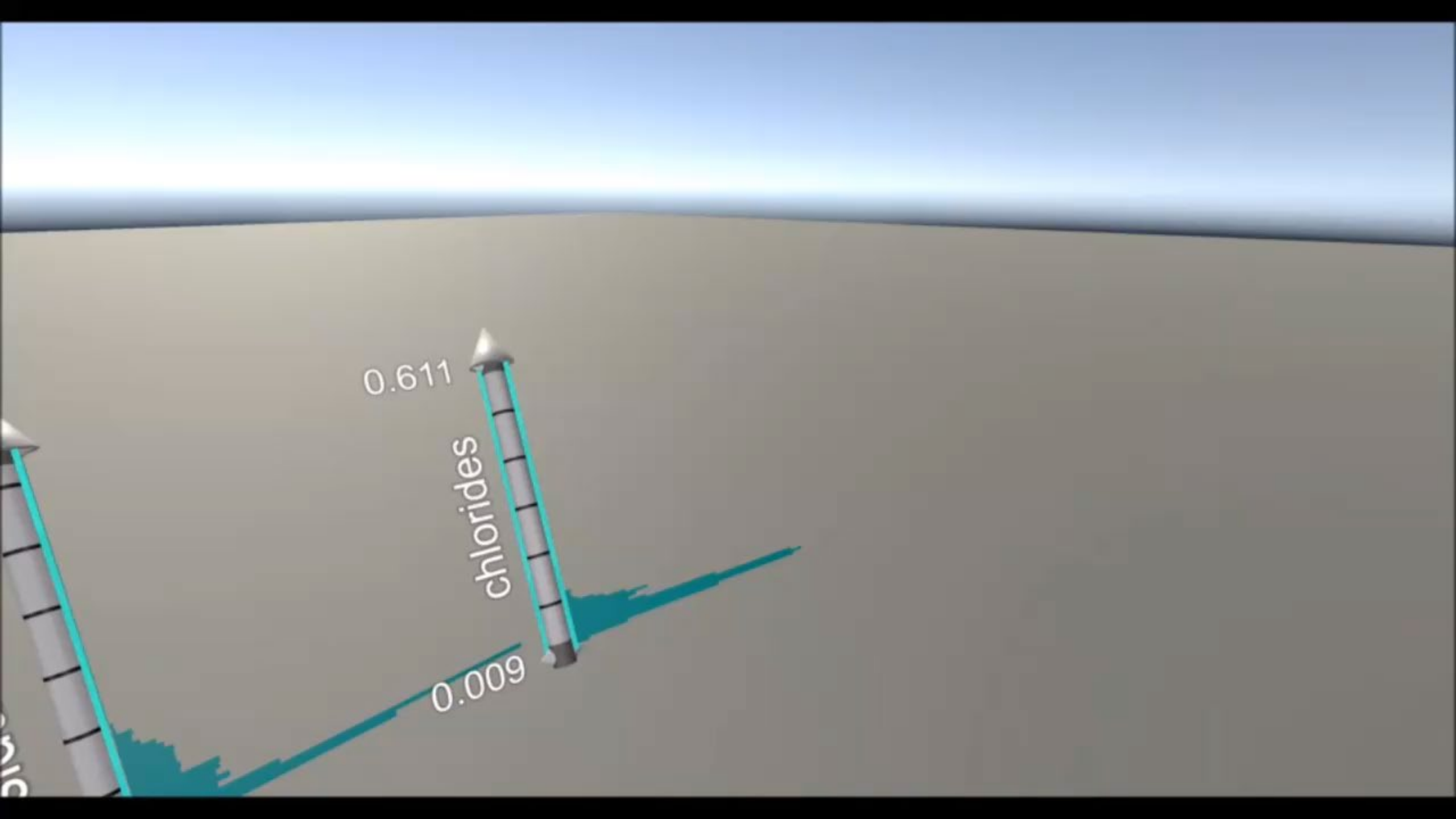
Tree of linked visualisations







Cloning an axis from the shelf



There Is No Spoon: Evaluating Performance, Space Use, and Presence with Expert Domain Users in Immersive Analytics

Andrea Batch, Andrew Cunningham, Maxime Cordeil, Niklas Elmqvist, *Senior Member, IEEE*,
Tim Dwyer, Bruce H. Thomas, *Senior Member, IEEE*, Kim Marriott



Fig. 1: Macroeconomics analysis in the ImAxes immersive analytics tool [11]. (Photo by Samuel Zeller on Unsplash.)

 master

 3 branches

 0 tags

Go to file

Add file

 Code

	MaximeCordeil Merge pull request #4 from MaximeCordeil/add-license-1	0187cb5 on 21 May 2019	🕒 43 commits
	Assets	fixed details on demand in 2D	2 years ago
	ProjectSettings	Initial checkin of project files	3 years ago
	.gitignore	Initial checkin of project files	3 years ago
	LICENSE	Create LICENSE	16 months ago
	README.md	Merge pull request #2 from tgdwyer/patch-3	2 years ago

README.md

ImAxes (1.0 beta)

ImAxes is an immersive data visualisation tool for multidimensional data exploration and analysis in virtual reality. [link](#)

About

Immersive visualisation tool for multidimensional data

 Readme

 MIT License

Releases

No releases published
[Create a new release](#)

Packages

No packages published
[Publish your first package](#)

https://github.com/MaximeCordeil/ImAxes



FiberClay

Sculpting Trajectory Queries

FibreClay – Immersive 3D curves exploration
Hurter, Riche, Drucker, **Cordeil**, Alligier, Vuillemot
IEEE InfoVis (TVCG) 19



Microsoft

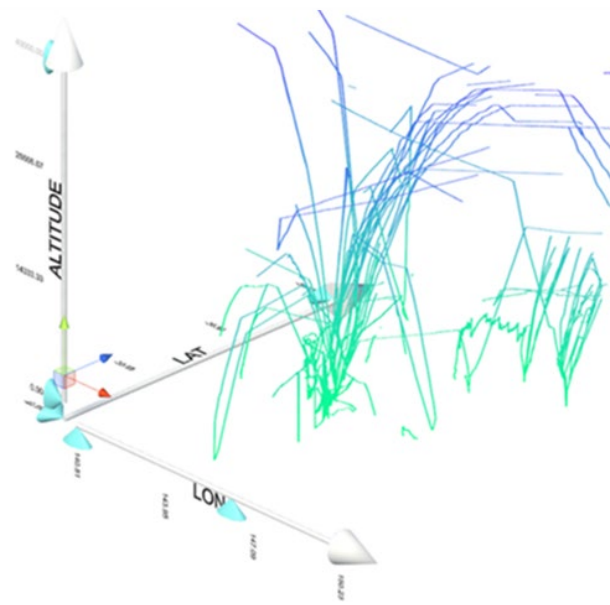
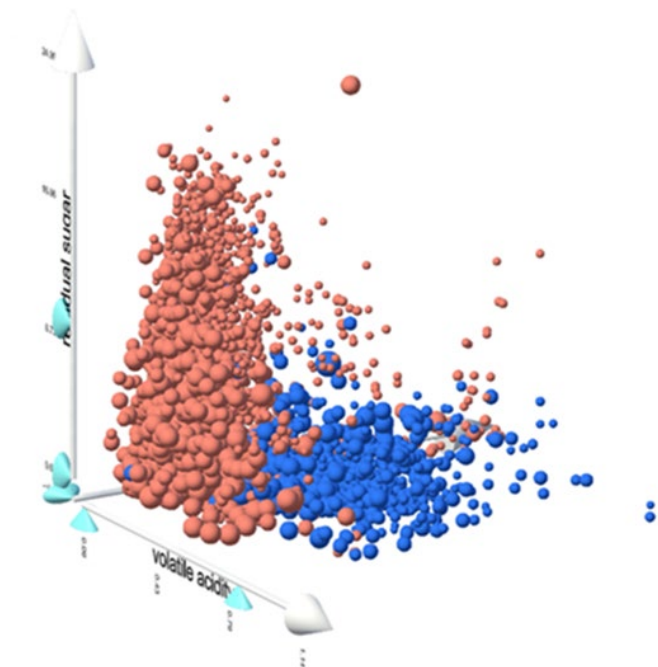
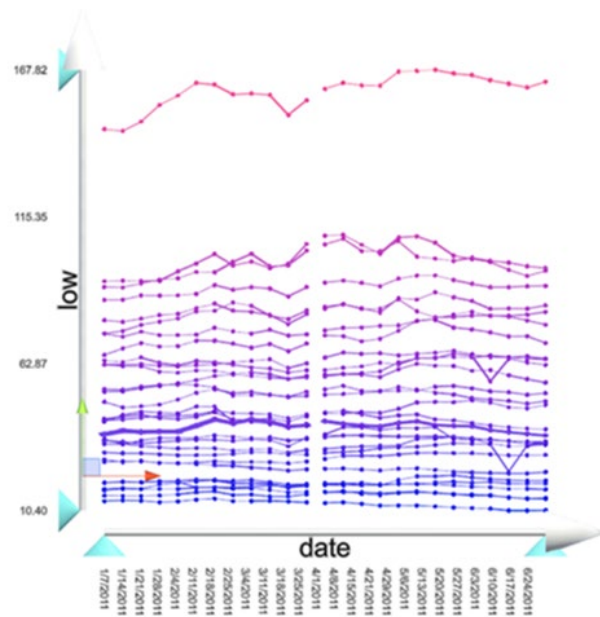
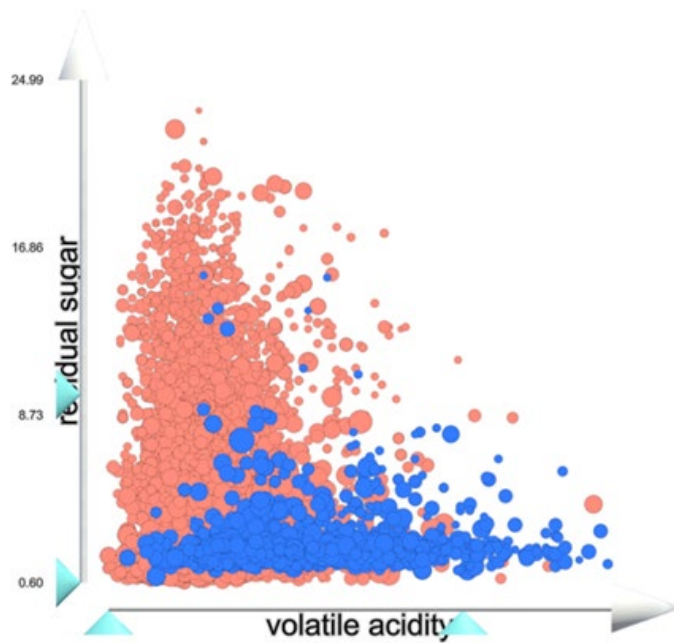


MONASH University
Information Technology

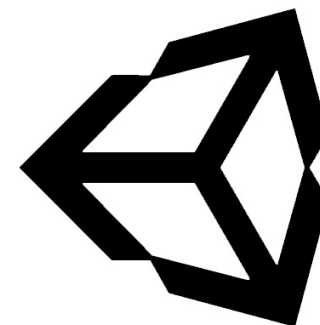
VIS library for immersive dev?

- No library readily available for InfoVis/VA in AR/VR
- Need for support of real dataset (i.e. support potential large datasets)
- Support standard VIS interactions/tasks (filtering, brushing, selection...)
- Default approach: instantiate GameObjects with default primitives... performance issues...

A full-body photograph of a woman standing against a plain white background. She is wearing a black VR headset with a strap, a black hoodie with a pink and white floral pattern, black leggings, and blue and pink sneakers. She is holding two blue VR controllers in front of her, one in each hand.



IATK



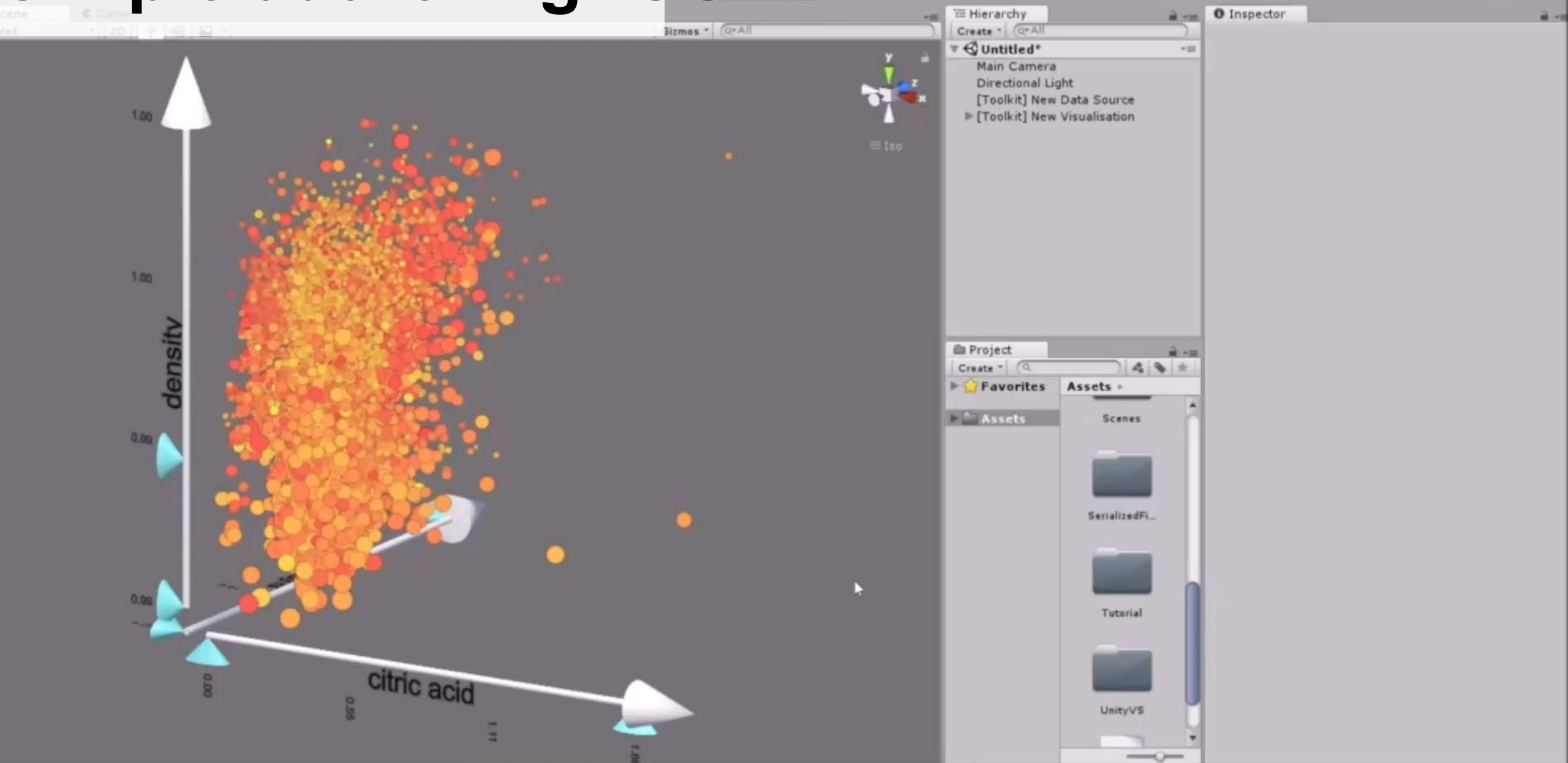
IATK design

+ expressiveness

+ expressiveness

+ simple authoring

simple authoring: GUI



simple authoring: API

// create a view builder with the point topology

```
ViewBuilder vb = new ViewBuilder (geometry, "visualisation name").  
    initialiseDataView(number_of_points).
```

simple authoring: API

// create a view builder with the point topology

```
ViewBuilder vb = new ViewBuilder (geometry, "visualisation name").
```

```
    initialiseDataView(number_of_points).
```

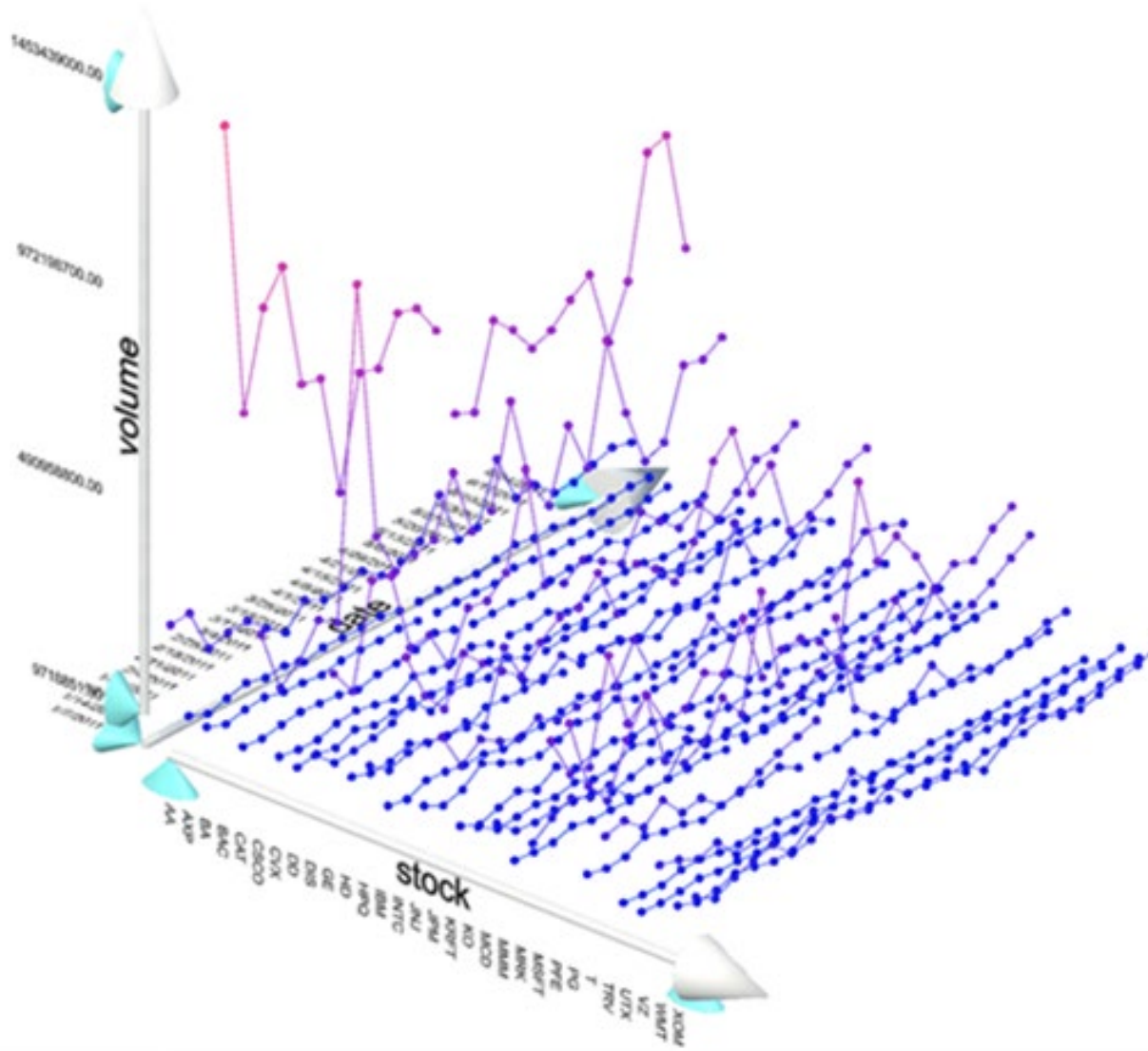
```
    setDataDimension(data_array_x, ViewBuilder.VIEW_DIMENSION.X).
```

```
    setDataDimension(data_array_y, ViewBuilder.VIEW_DIMENSION.Y).
```

```
    setDataDimension(data_array_z, ViewBuilder.VIEW_DIMENSION.Z).
```

simple auth

```
// create a view b  
ViewBuilder vb =  
    initialise  
    setData  
    setData  
    setData  
    setSize(  
    setColor
```



ion name”).

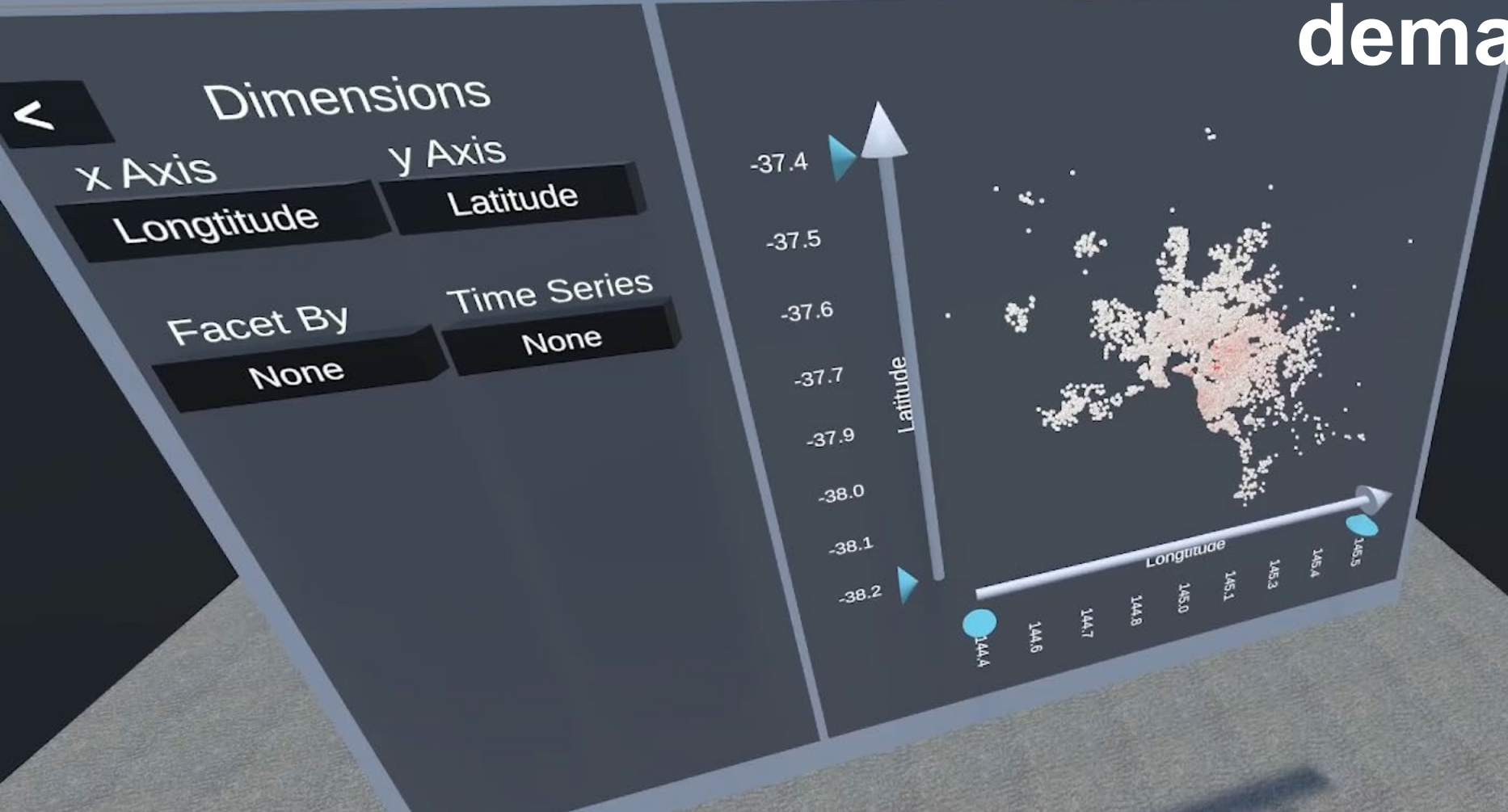
EW_DIMENSION.X).
EW_DIMENSION.Y).
EW_DIMENSION.Z).

a point
h data point

- + expressiveness
- + simple authoring
- + interaction

Colour By: Price

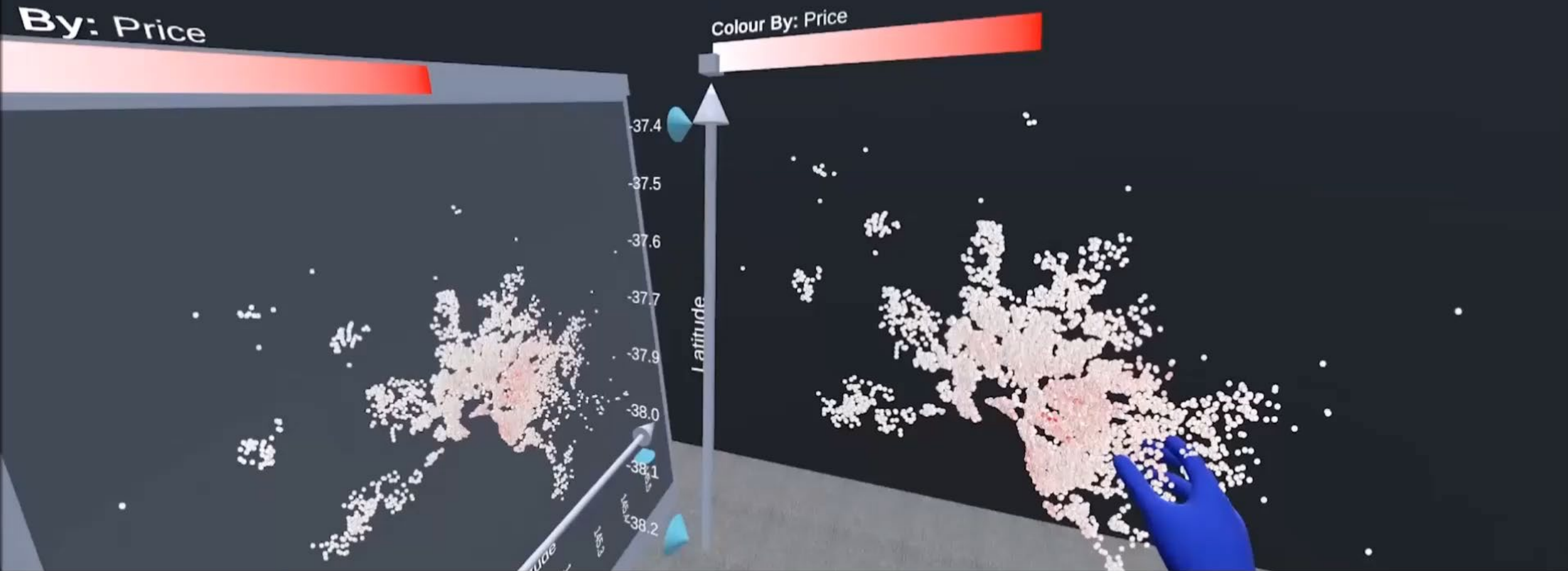
details on
demand



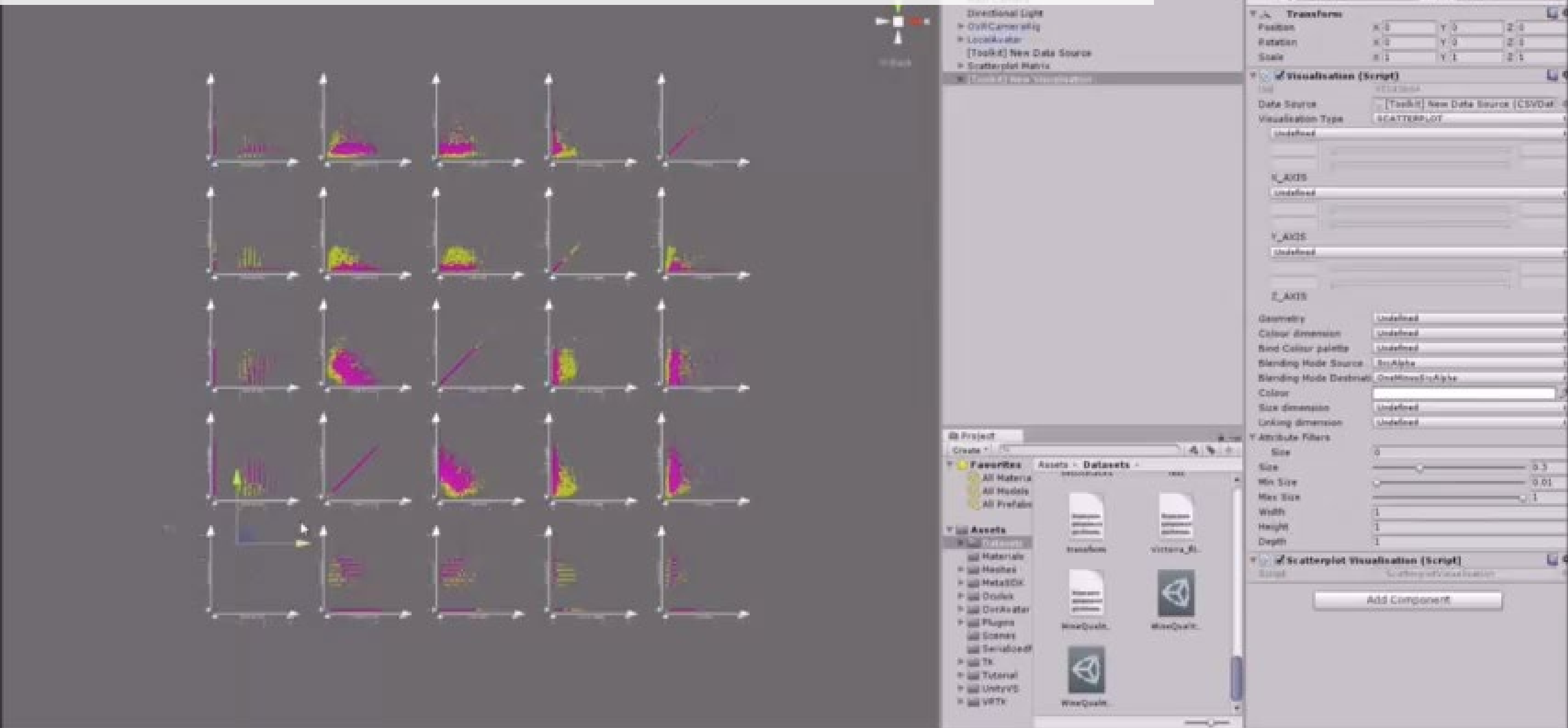
filtering

By: Price

Colour By: Price

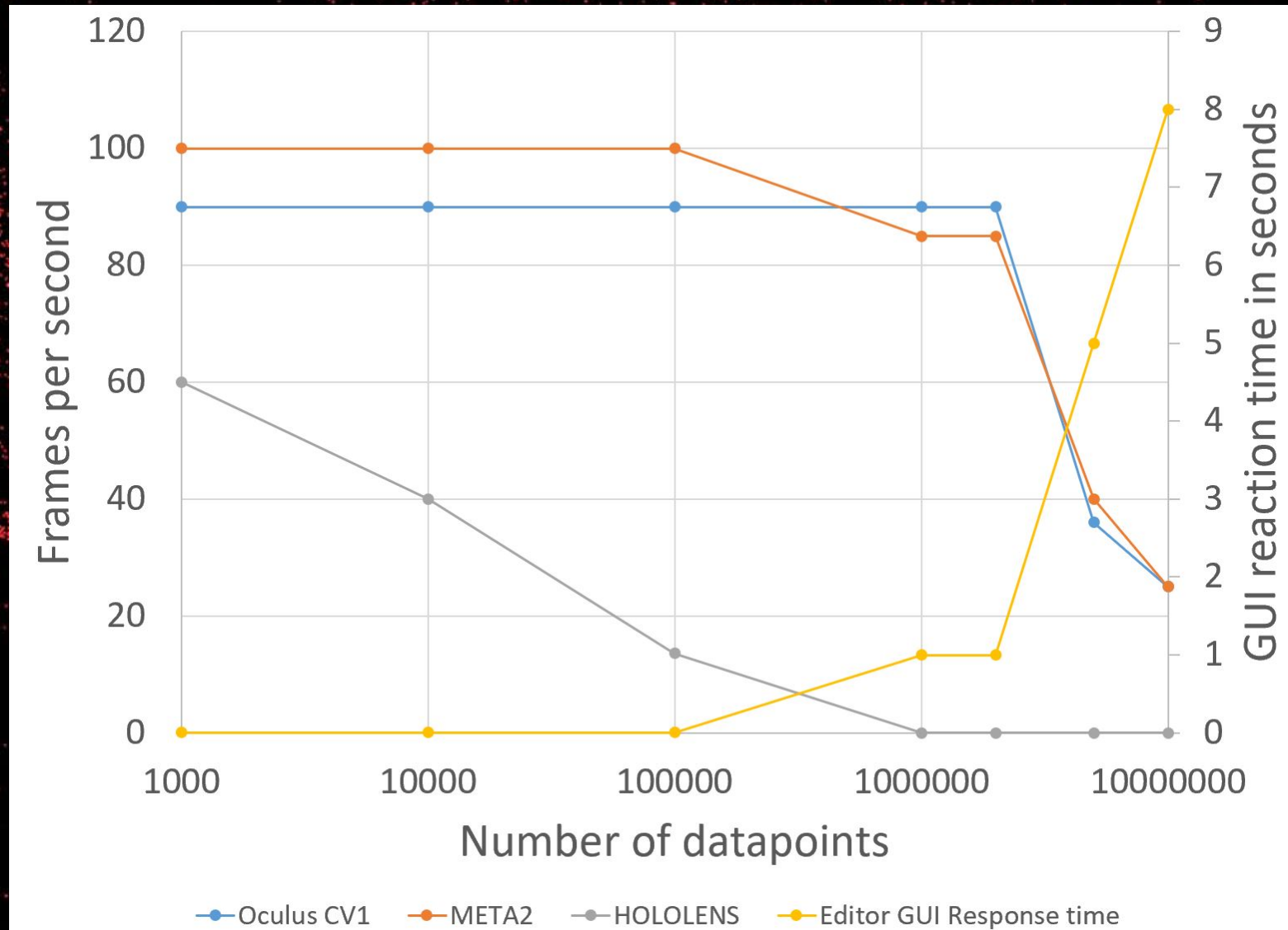


brushing and linking



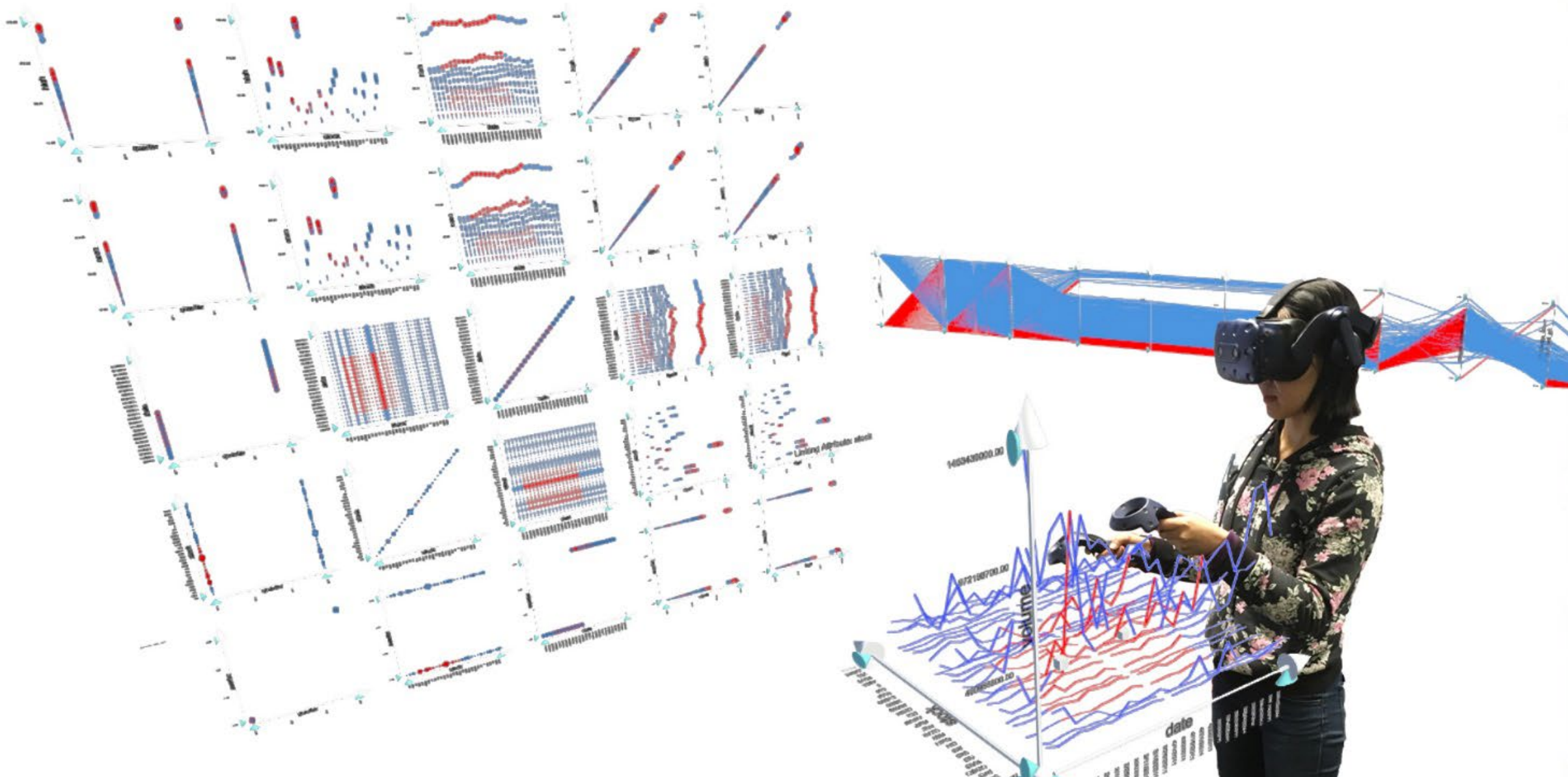
- + expressiveness
- + simple authoring
- + interaction
- + scalability

scalability



use case examples

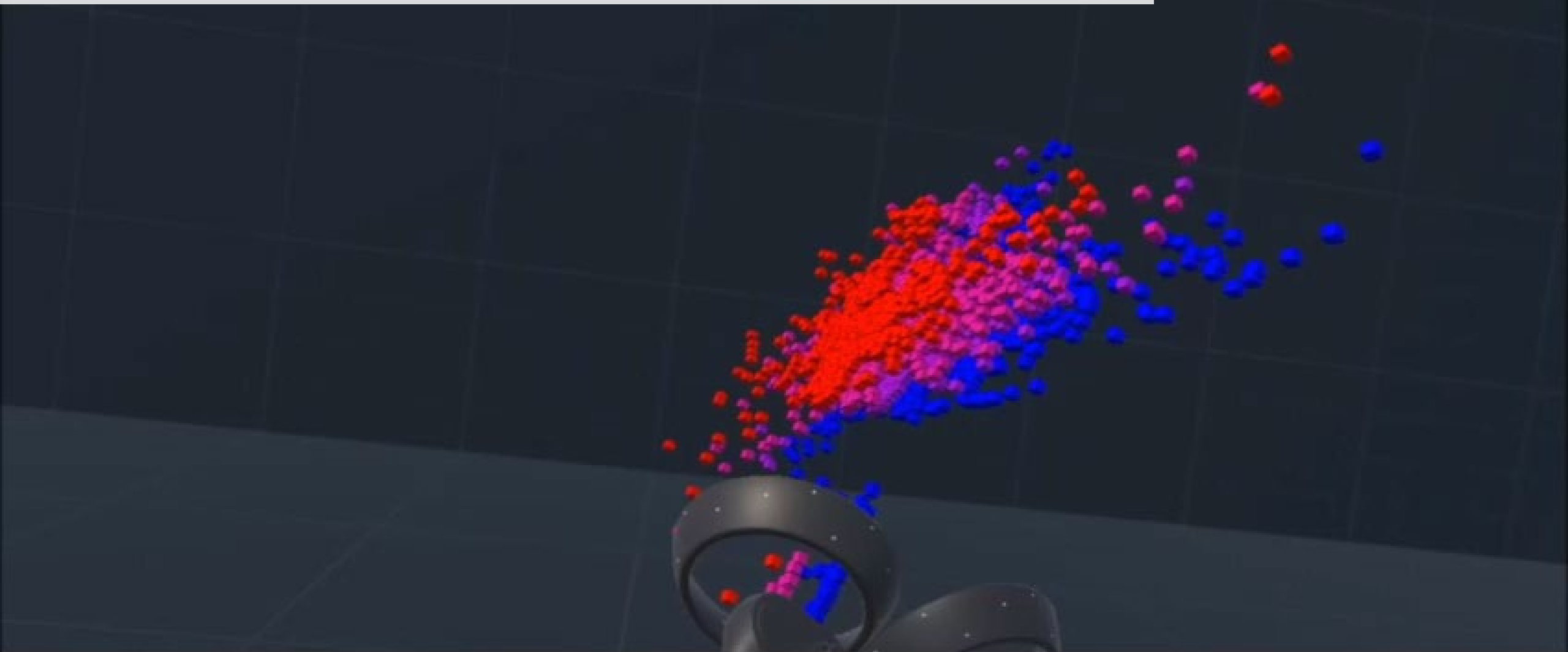
multivariate visualisation in VR



AR desktop for geoviz



emerging interactions



Simple Interaction

- Attach a visualisation to a controller

MapBox integration

Scene

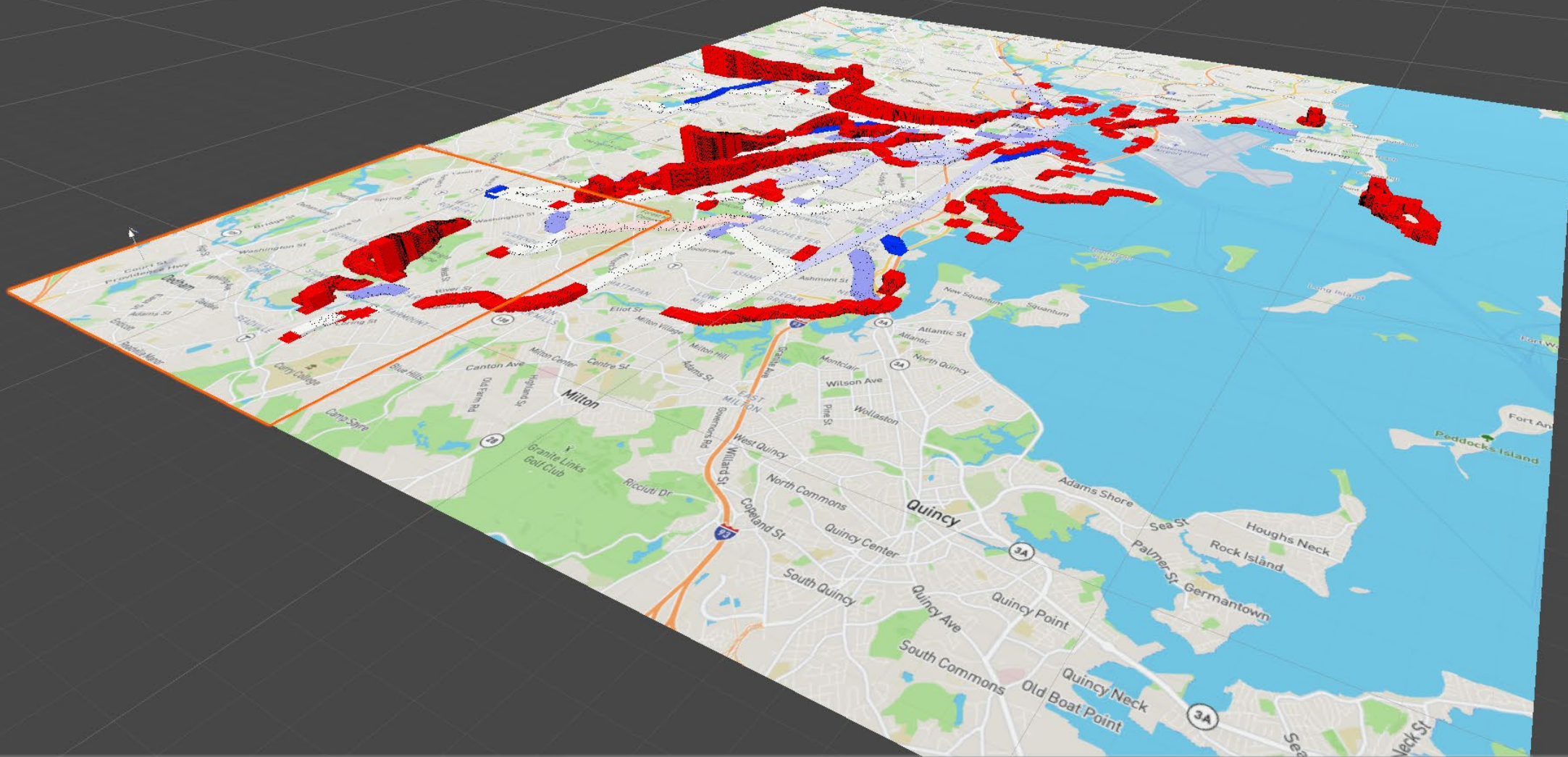
Shaded

2D



Gizmos

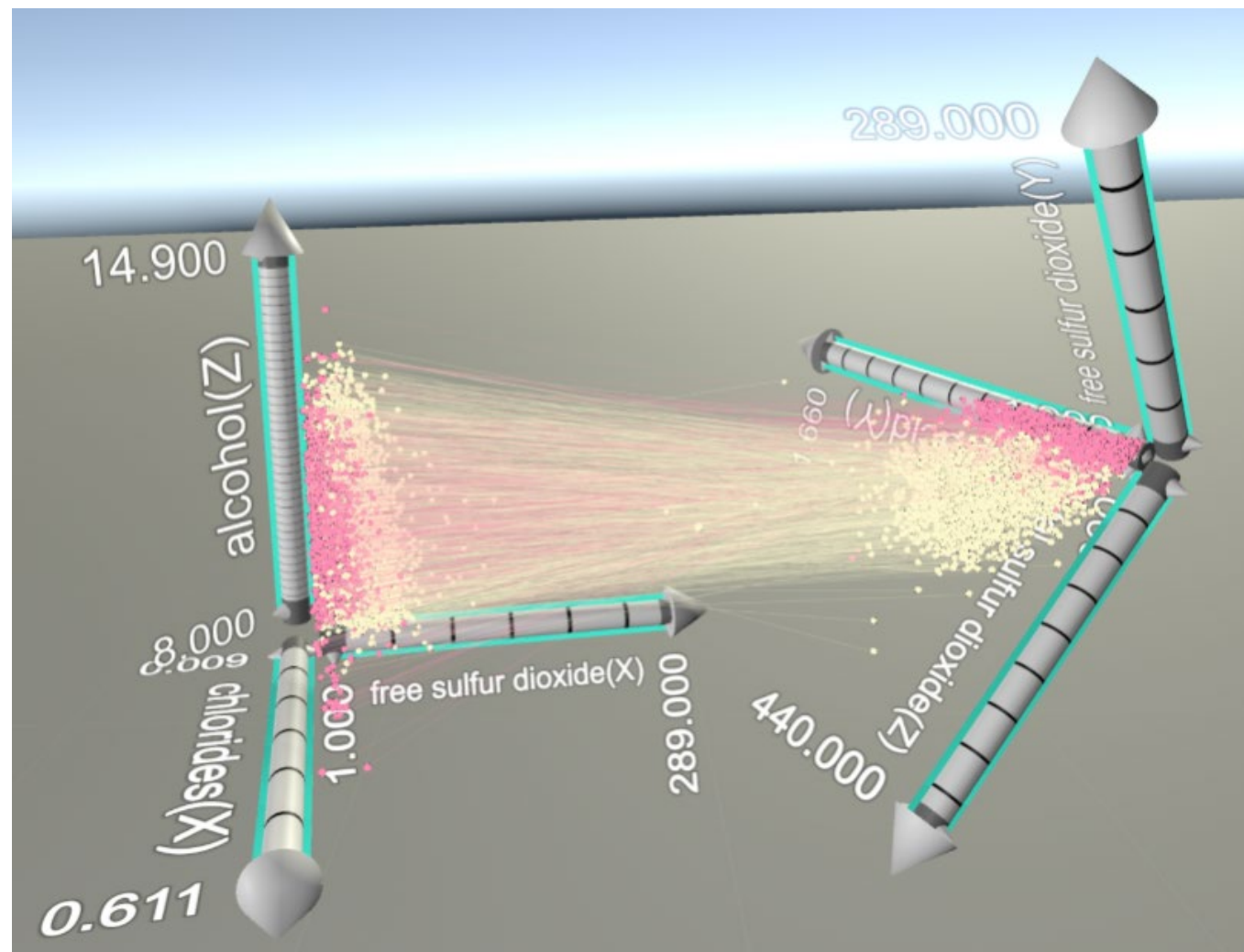
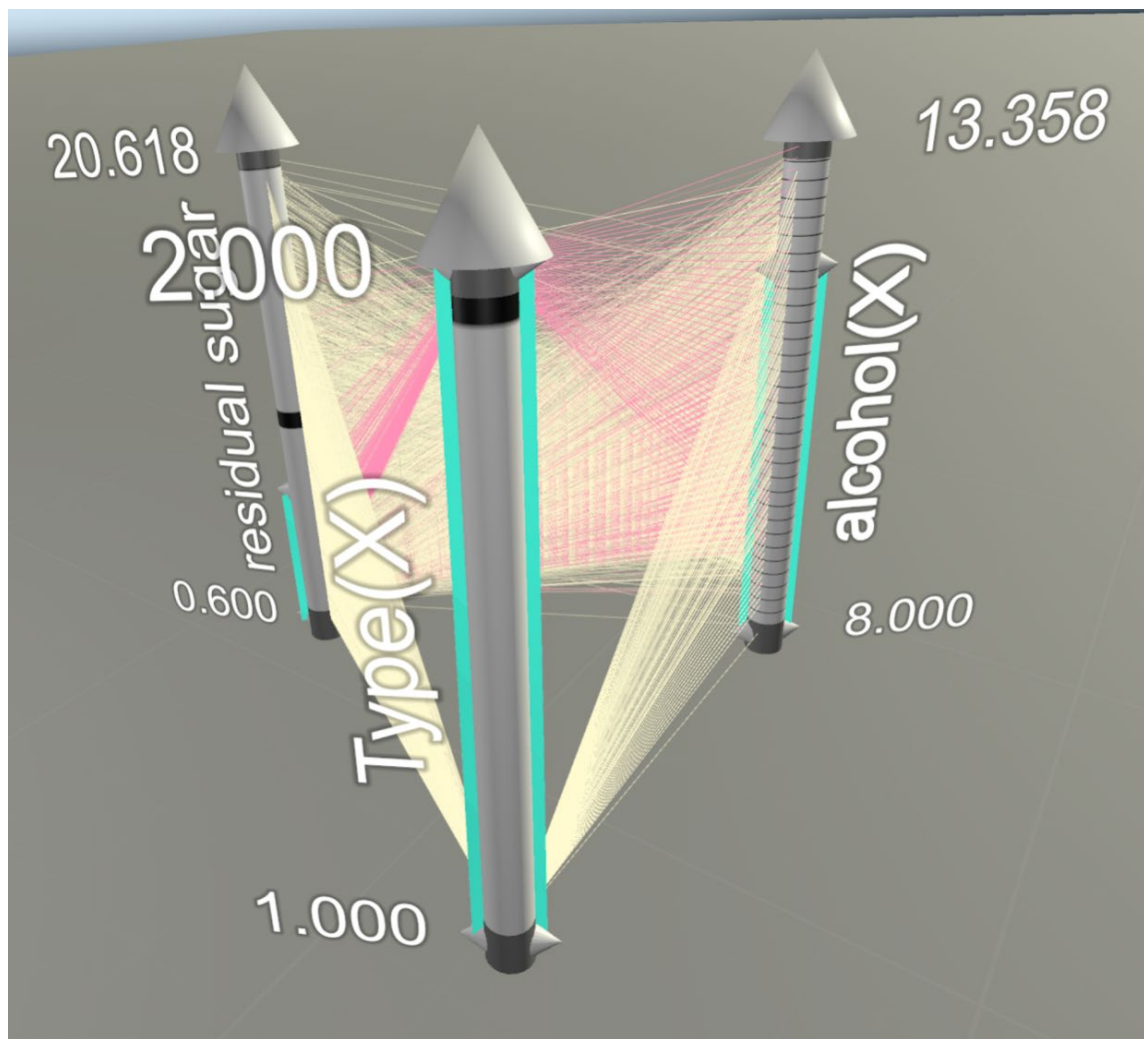
All



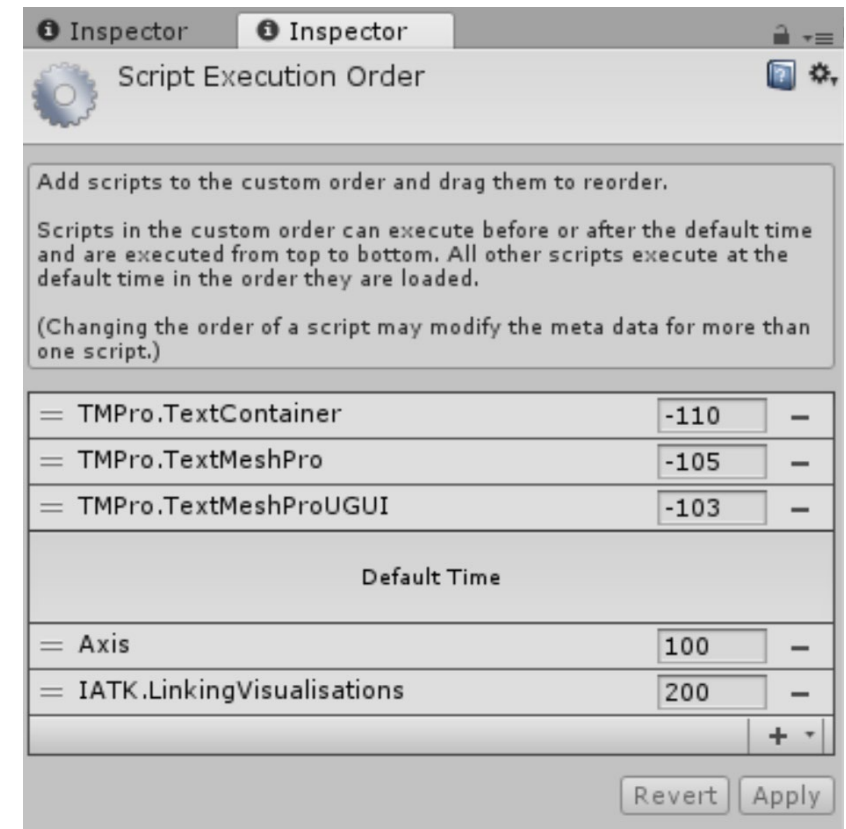
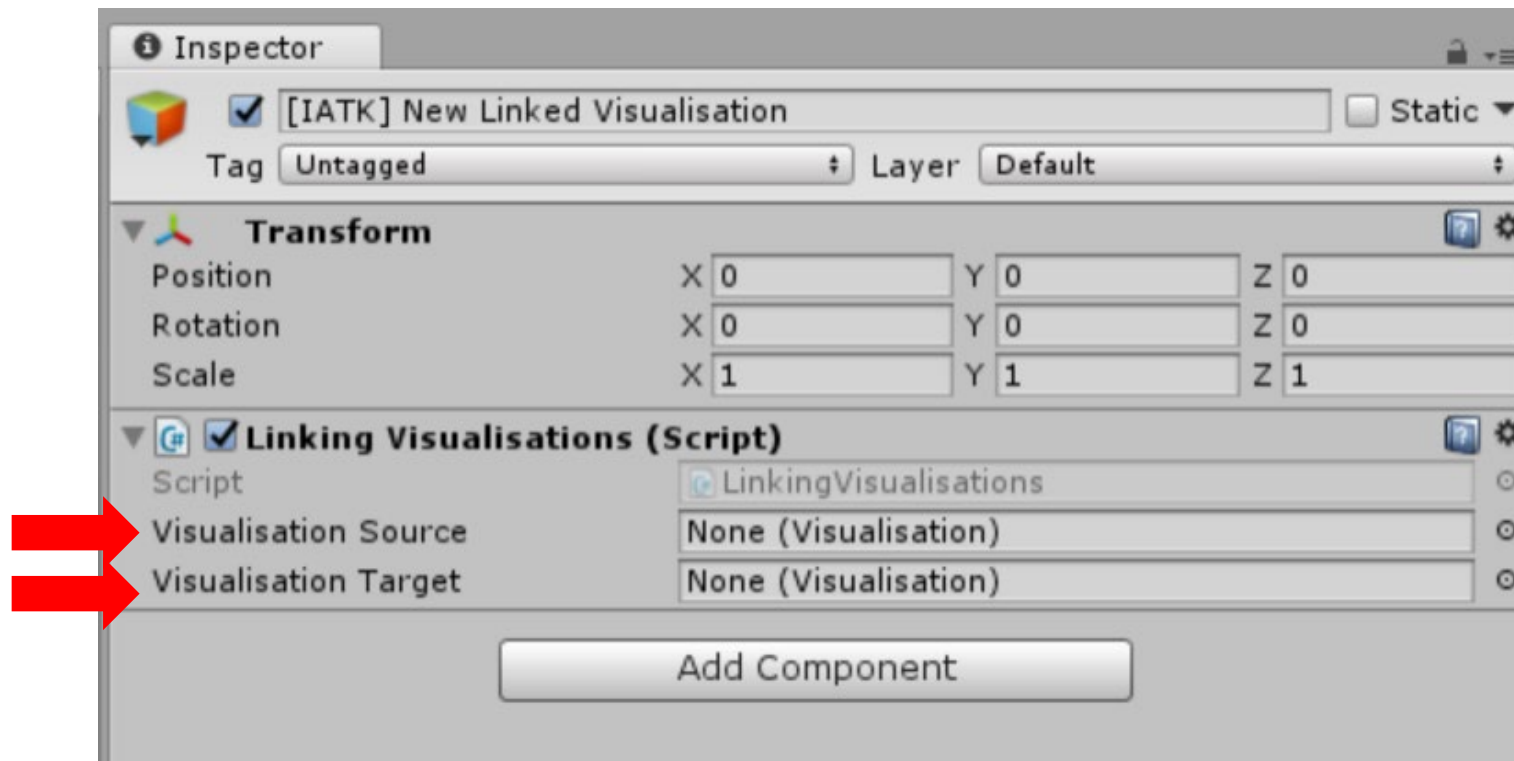
Game

- Visualise geo data
- Bike path boston -> build the visu
- Add a Map Visualisation IATK component
- Make sure X,Z (planar) dimensions correspond to lat/lon
- Drag and drop:
 - The visualisation reference
 - The datasource reference

Linked visualisations



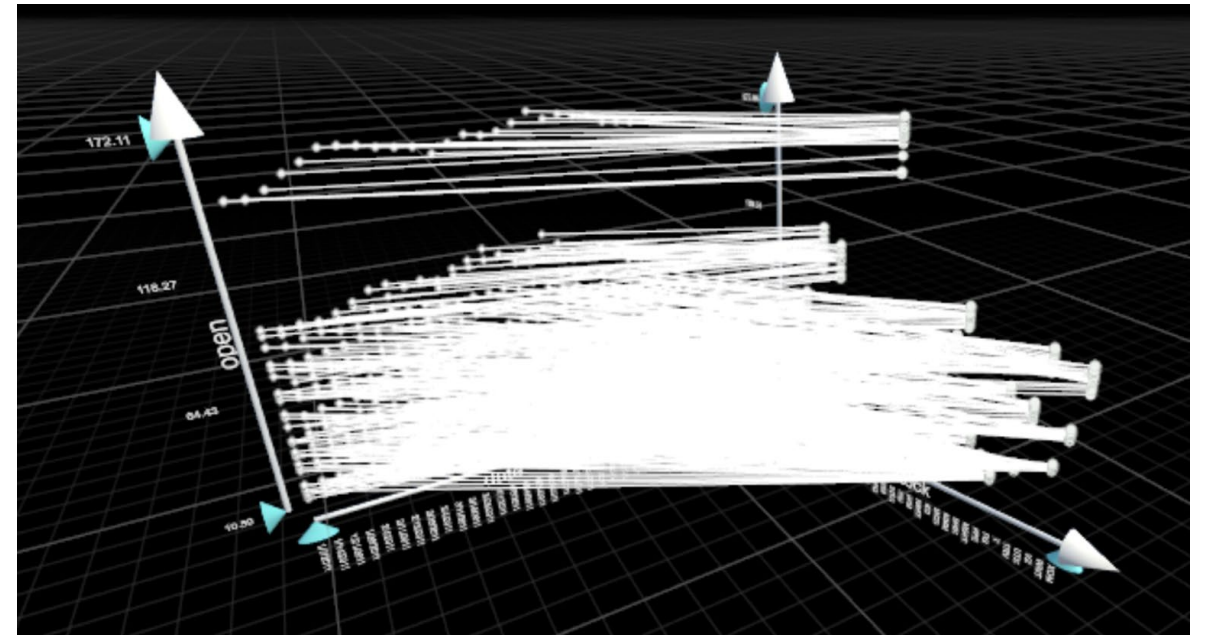
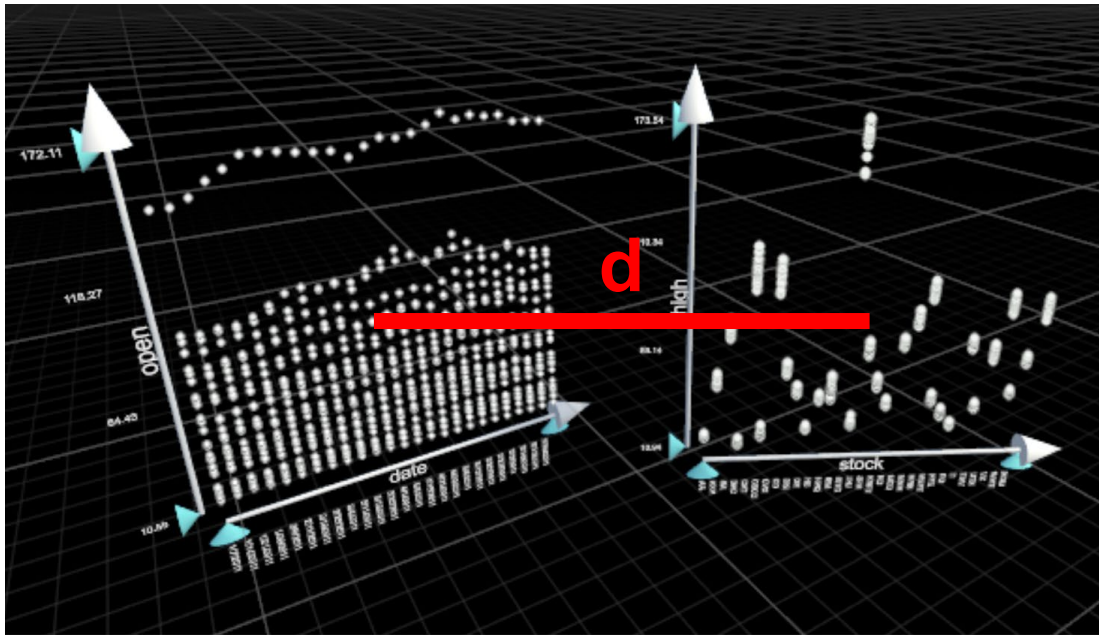
[IATK] *Linked Visualisation* component



Edit > Project Settings > Script Execution Order

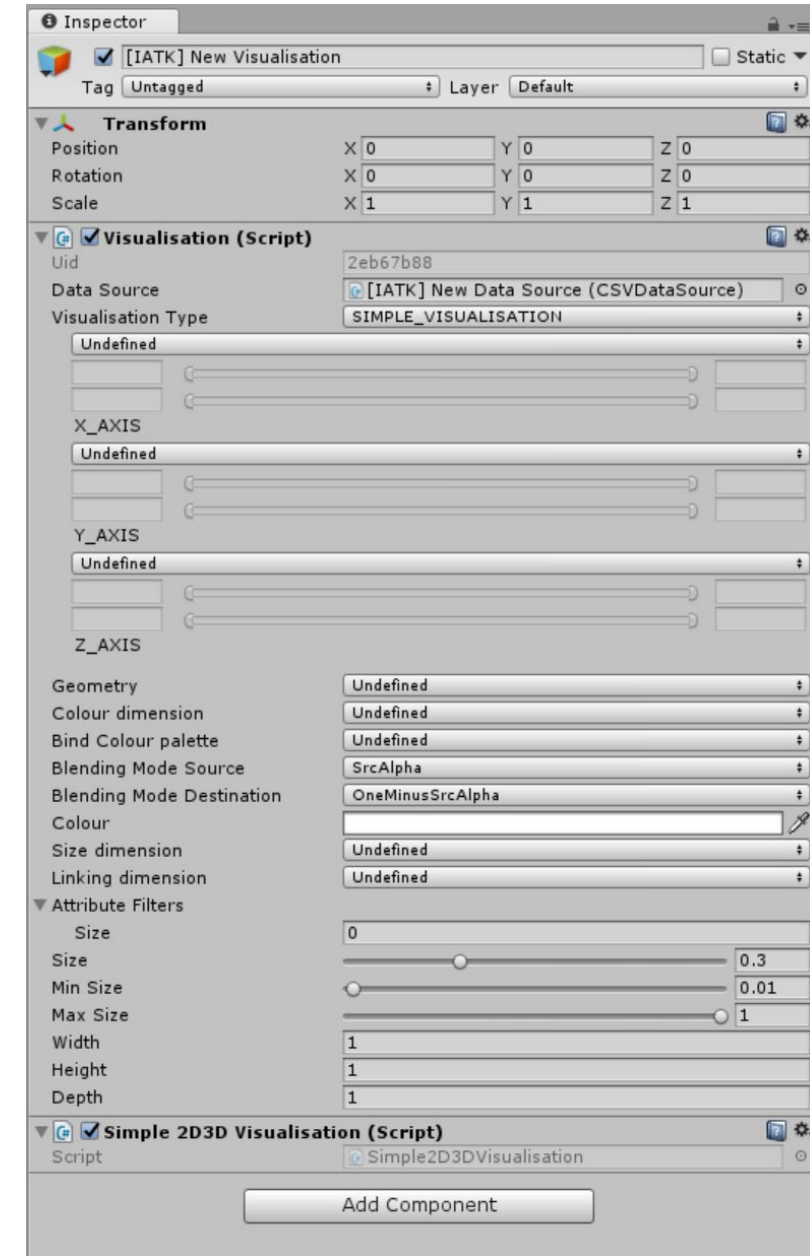
Activity 5: Linked visualisations

make a simple script that links the visualisations when they are below a certain distance d .



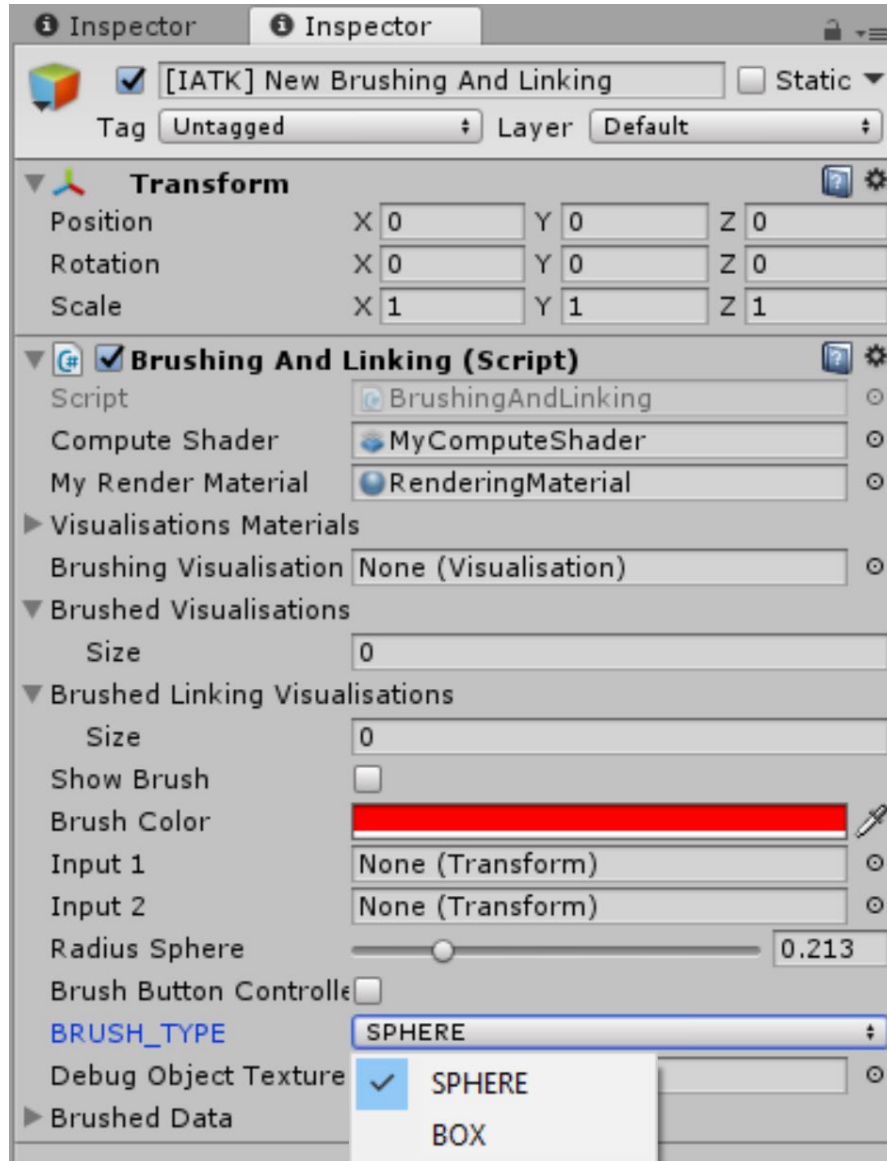
Activity 6: Attribute Animation

write a custom *MonoBehaviour* script to control a *Visualisation* component

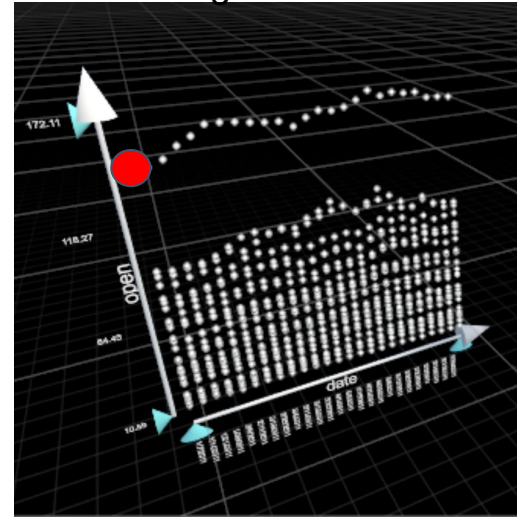


Brushing and linking

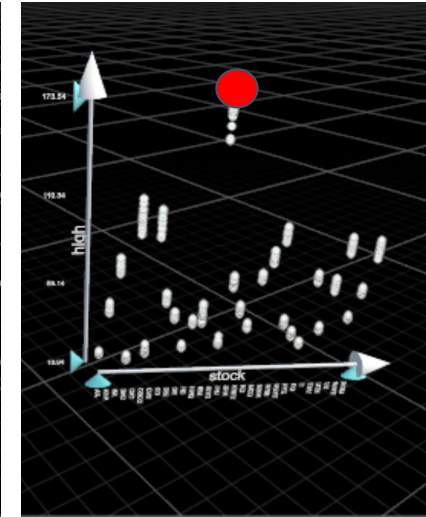
[IATK] *Brushing And Linking* component



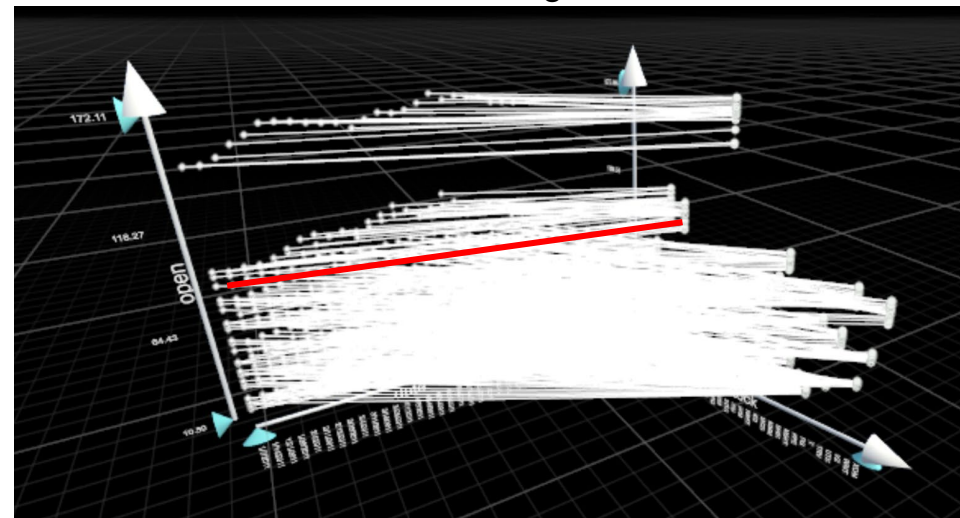
brushing visualisation



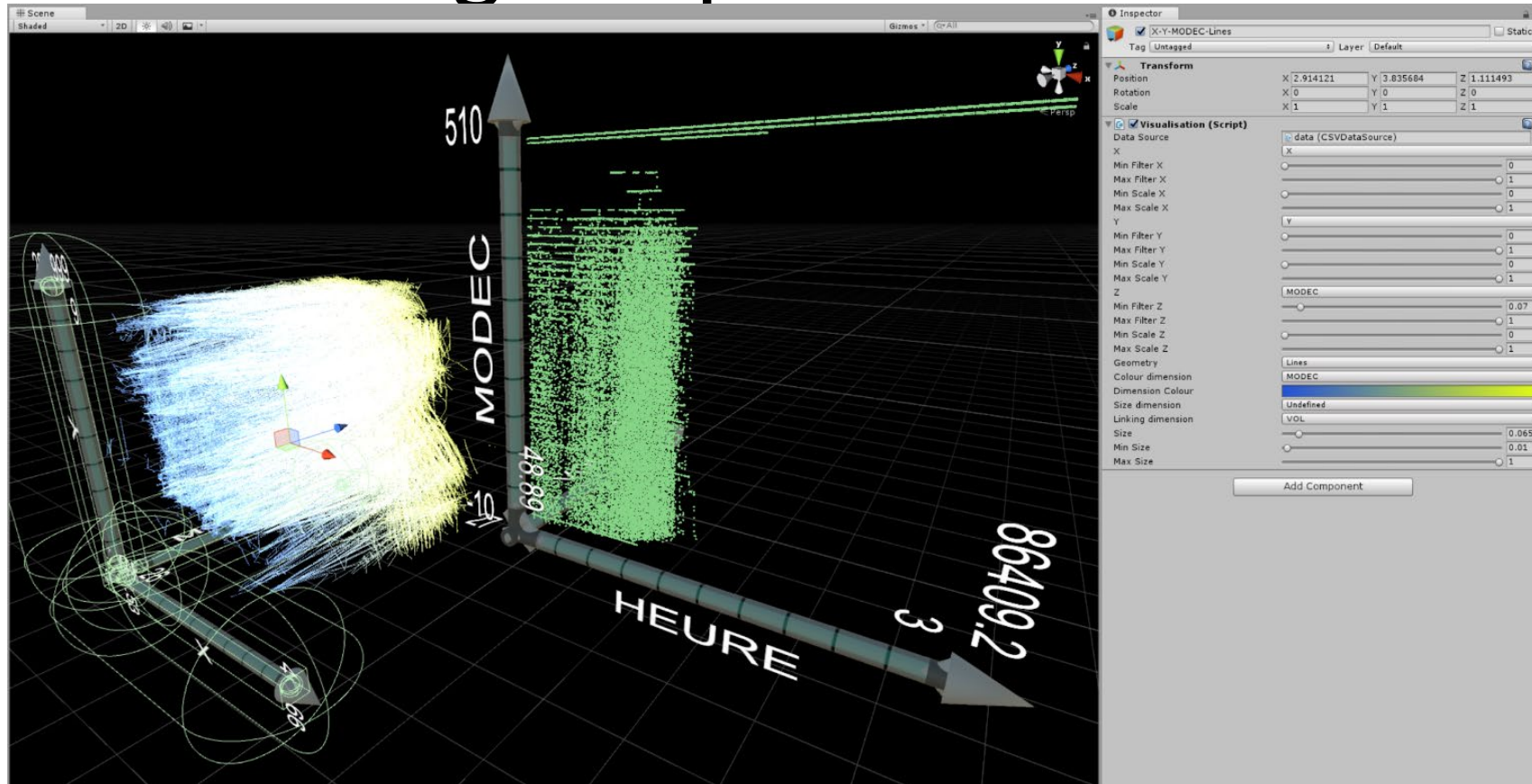
brushed visualisation



Brushed Linking Visualisation



Demo: brushing 1M points



Dataset from Hurter, Christophe, Benjamin Tissoires, and Stéphane Conversy. "FromDaDy: Spreading data across views to support iterative exploration of aircraft trajectories." *IEEE TVCG* 15.6 (2009): 1017-1024.

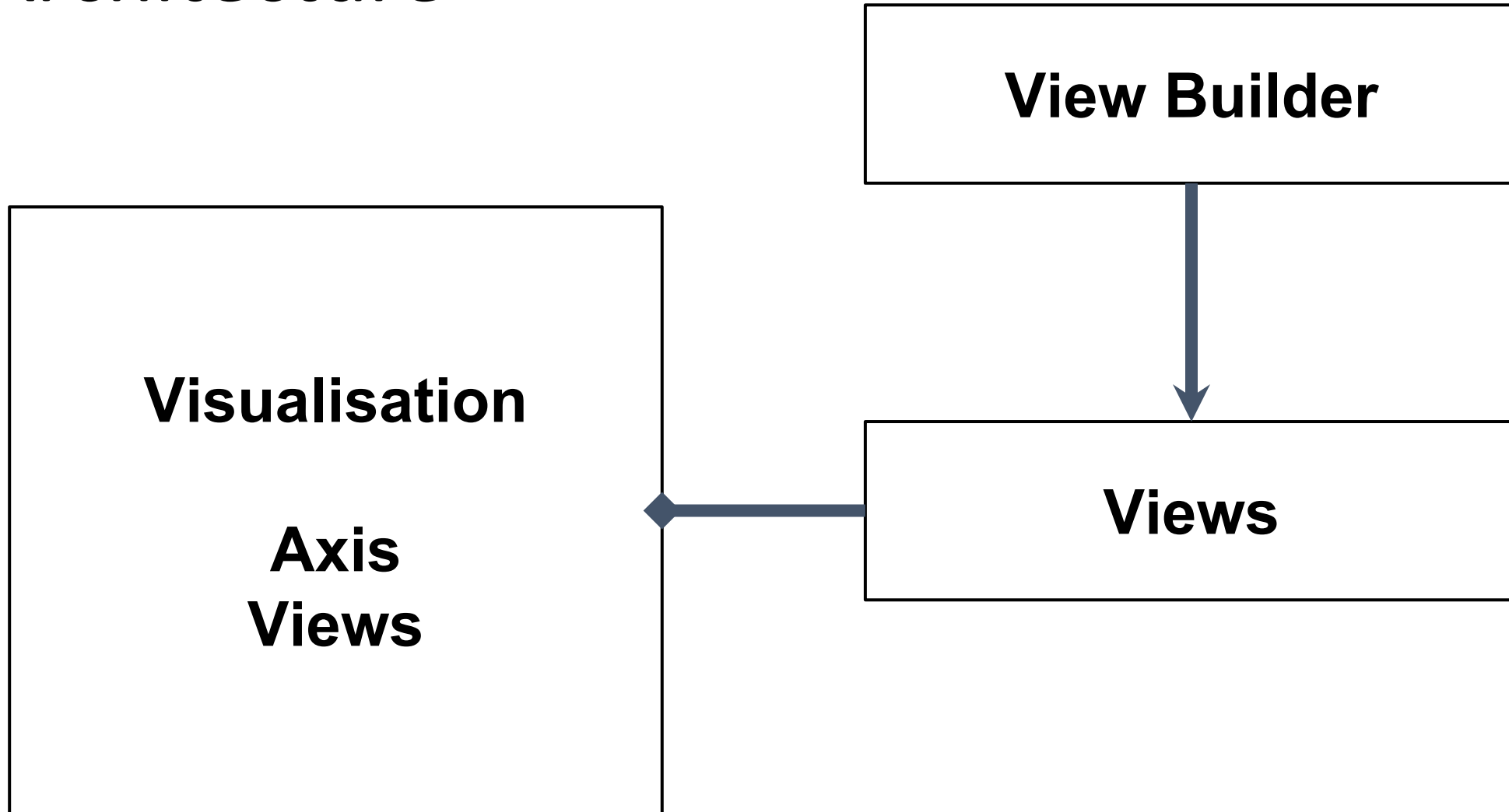
[IATK] core code

In this section, you'll...

- Learn the underlying architecture of IATK
- Build a scatterplot visualisation using code
- Facet data and build multiple views
- Create a novel accordian interaction



Architecture



[IATK] ViewBuilder.cs and View.cs

- ViewBuilder.cs: fluent interface design pattern (d3-like)
 - Chain design commands
- ```
object.DoSomething().
 DoSomething2().
 DoSomething3();
```

## C# LINQ facility

- transform input data (e.g. on dimensions, sizes ...)
- map data to colours
- map data to categories
- filters, set operations

# CSVDatasource - code snippet

// Use Unity Test assets to import text data (e.g. csv, tsv etc.)

```
public TextAsset uberData;
```

```
CSVDataSource csvdata;
```

```
csvdata = createCSVDataSource(uberData.text);
```

```
CSVDataSource createCSVDataSource(string data)
```

```
{
```

```
 CSVDataSource dataSource = gameObject.AddComponent<CSVDataSource>();
```

```
 dataSource.load(data, null);
```

```
 return dataSource;
```

```
}
```

# ViewBuilder - structure

// create a view builder with the point topology

**ViewBuilder** vb = **new ViewBuilder** (*a topology, a name*).

    initialiseDataView(*number of points*).

    setDataDimension(*data array x*, ViewBuilder.VIEW\_DIMENSION.X).

    setDataDimension(*data array y*, ViewBuilder.VIEW\_DIMENSION.Y).

    setDataDimension(*data array z*, ViewBuilder.VIEW\_DIMENSION.Z).

    setSize(*data array size*).

        setColors(*data array color*);

# ViewBuilder - basic code snippet (points)

// create a view builder with the point topology

```
ViewBuilder vb = new ViewBuilder (MeshTopology.Points, "Uber pick up point visualisation").
 initialiseDataView(csvds.DataCount).
 setDataDimension(csvds["Lat"].Data, ViewBuilder.VIEW_DIMENSION.X).
 setDataDimension(csvds["Base"].Data, ViewBuilder.VIEW_DIMENSION.Y).
 setSize(csvds["Base"].Data).
 setColors(csvds["Time"].Data.Select(x => g.Evaluate(x)).ToArray());
```

// create a view builder with the point topology

```
View view = vb.updateView().apply(gameObject, mt);
```

# ViewBuilder - basic code snippet (points)

// create a view builder with the point topology

```
ViewBuilder vb = new ViewBuilder (MeshTopology.Points, "Uber pick up point visualisation").
 initialiseDataView(csvds.DataCount).
 setDataDimension(csvds["Lat"].Data, ViewBuilder.VIEW_DIMENSION.X).
 setDataDimension(csvds["Base"].Data, ViewBuilder.VIEW_DIMENSION.Y).
 setDataDimension(csvds["Lon"].Data, ViewBuilder.VIEW_DIMENSION.Z).
 setSize(csvds["Base"].Data).
 setColors(csvds["Time"].Data.Select(x => g.Evaluate(x)).ToArray());
```

// create a view builder with the point topology

```
View view = vb.updateView().apply(gameObject, mt);
```

# ViewBuilder - basic code snippet (line chart)

```
// create a view builder with the point topology
```

```
ViewBuilder vb = new ViewBuilder(MeshTopology.Lines, "Uber pick up point visualisation").
```

```
 initialiseDataView(csvds.DataCount).
```

```
 setDataDimension(csvds["stock"].Data, ViewBuilder.VIEW_DIMENSION.X).
```

```
 setDataDimension(csvds["date"].Data, ViewBuilder.VIEW_DIMENSION.Y).
```

```
 setDataDimension(csvds["open"].Data, ViewBuilder.VIEW_DIMENSION.Z).
```

```
 setSize(csvds["volume"].Data).
```

```
 setColors(csvds["volume"].Data.Select(x => g.Evaluate(x)).ToArray()).
```

```
 createIndicesLinkedTopology(csvds["stock"].Data);
```

```
// create a view builder with the point topology
```

```
Material mt = IATKUtil.GetMaterialFromTopology(AbstractVisualisation.GeometryType.Lines);
```

```
mt.SetFloat("_MinSize", 0.01f);
```

```
mt.SetFloat("_MaxSize", 0.05f);
```

```
View view = vb.updateView().apply(gameObject, mt);
```

# ViewBuilder - filtering with Linq

// use delegate to filter data

```
delegate float[] Filter(float[] ar, CSVDataSource csvds, string filteredValue, string filteringAttribute);
```

// filters the array on a particular value in another dimension

```
Filter baseFilter = (array, datasource, value, dimension) =>
{
 return array.Select((b, i) => new { index = i, _base = b })
 .Where(b => datasource.getOriginalValuePrecise(csvds[dimension].Data[b.index],dimension).ToString() == value)
 .Select(b => b._base).ToArray();
};
```

# ViewBuilder - apply filter

```
var xData = baseFilter(csvds["Lat"].Data,csvds, _fv);
var yData = baseFilter(csvds["Lon"].Data, csvds, _fv);
var zData = baseFilter(csvds["Base"].Data, csvds, _fv);
```

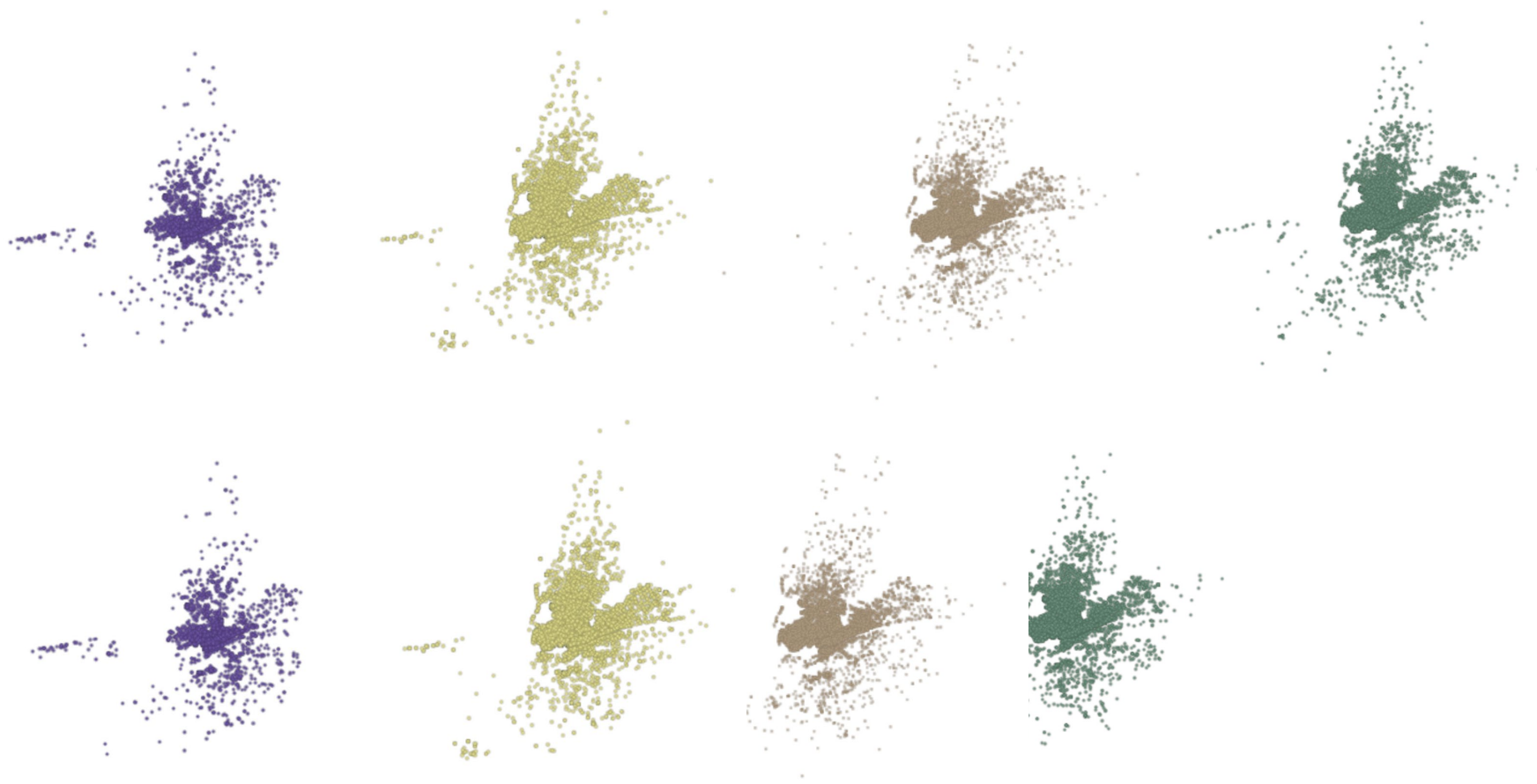
```
ViewBuilder vb = new ViewBuilder(MeshTopology.Points, "Uber pick up point visualisation").
 initialiseDataView(xData.Length).
 setDataDimension(xData, ViewBuilder.VIEW_DIMENSION.X).
 setDataDimension(yData, ViewBuilder.VIEW_DIMENSION.Y).
 setDataDimension(zData, ViewBuilder.VIEW_DIMENSION.Z).
 setSize(baseFilter(csvds["Date"].Data,csvds, _fv)).
 setColors(xData.Select(x => color).ToArray());
```

# Activity - faceting

- use filters to create faceted data
- control faceted objects positions



# Activity - accordion faceting!

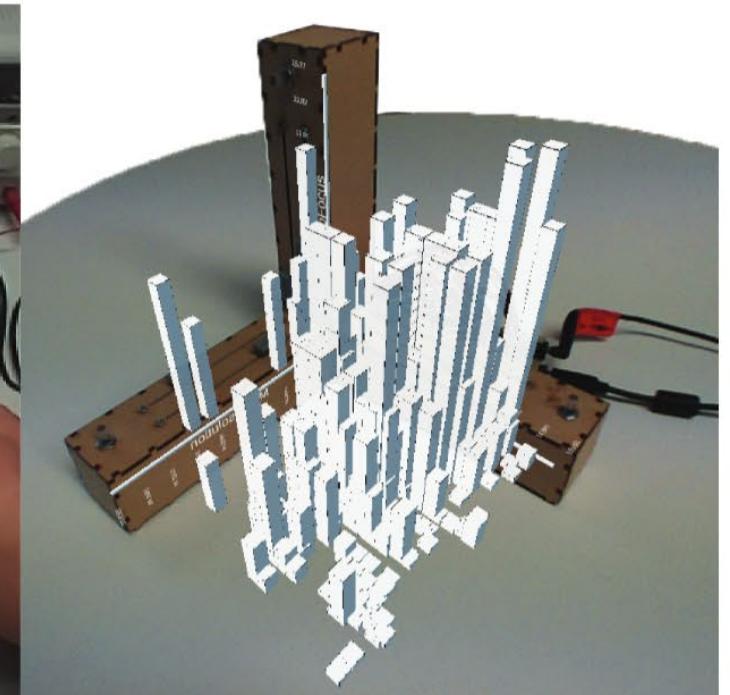
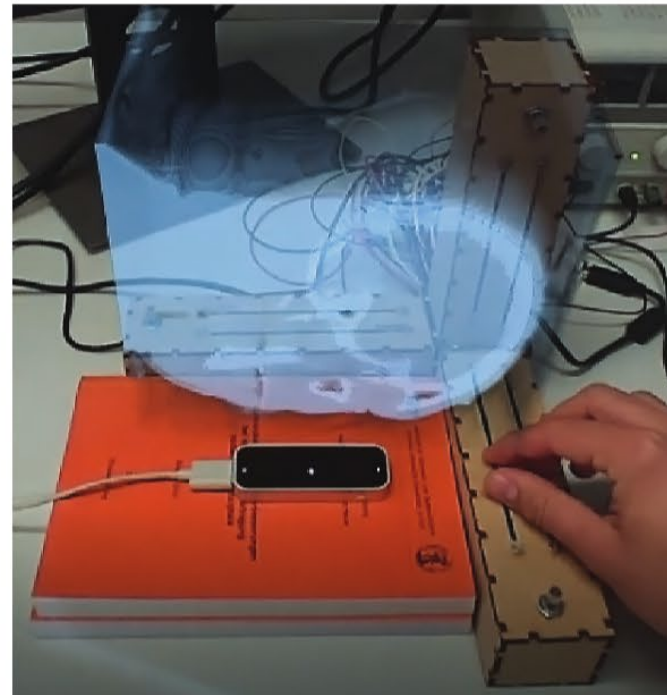
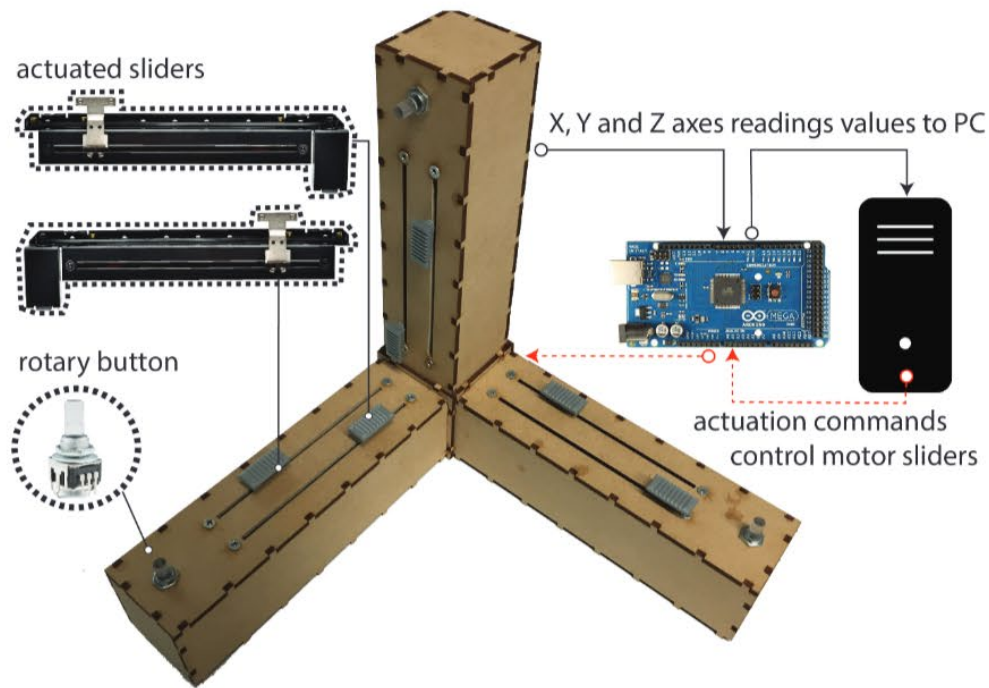


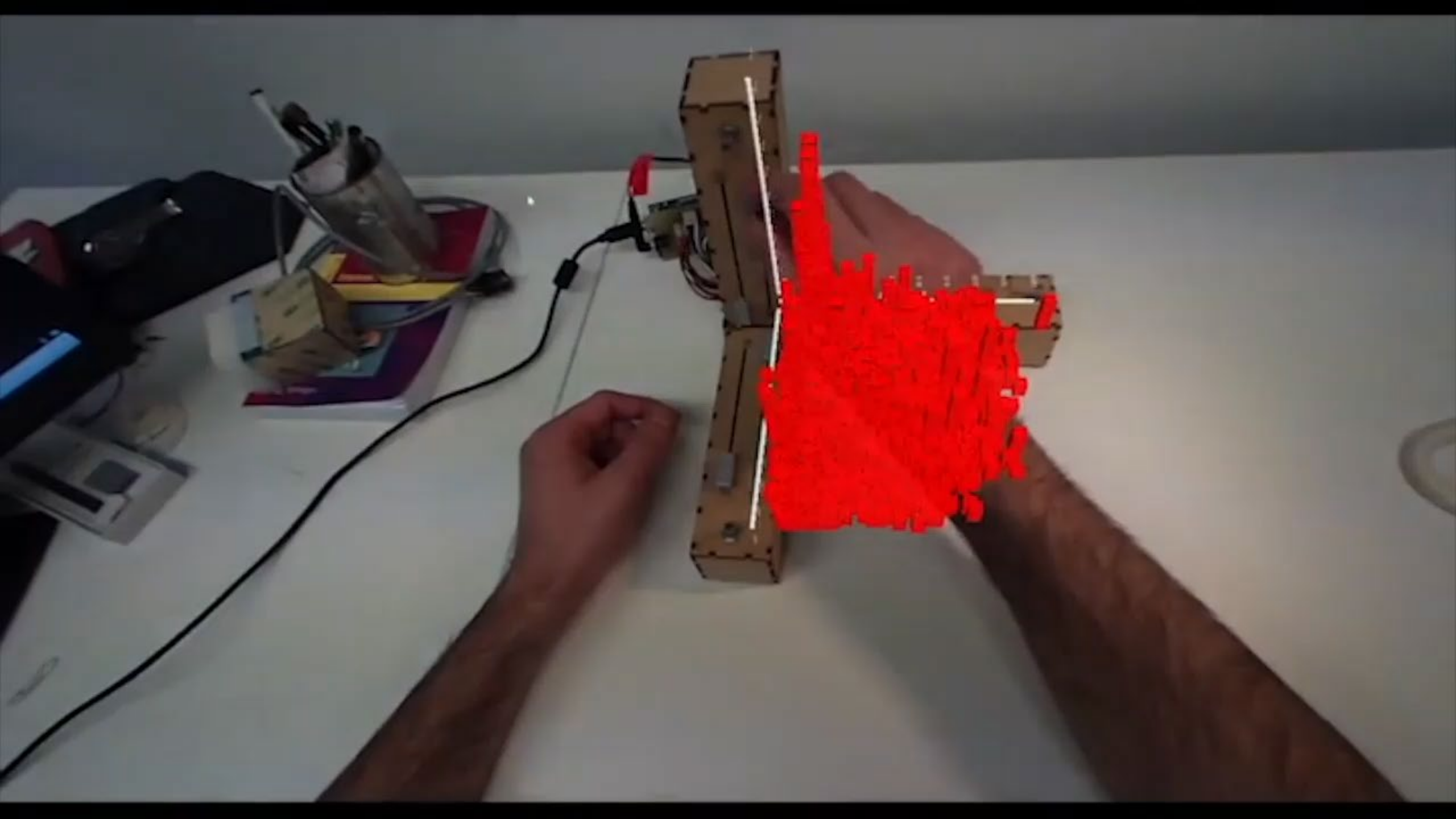
Built with IATK

# Embodied Axes: Tangible, Actuated Interaction for 3D Augmented Reality Data Spaces

Maxime Cordeil<sup>1</sup>, Benjamin Bach<sup>2</sup>, Andrew Cunningham<sup>3</sup>, Bastian Montoya<sup>3</sup>,  
Ross T. Smith<sup>3</sup>, Bruce H. Thomas<sup>3</sup>, Tim Dwyer<sup>1</sup>

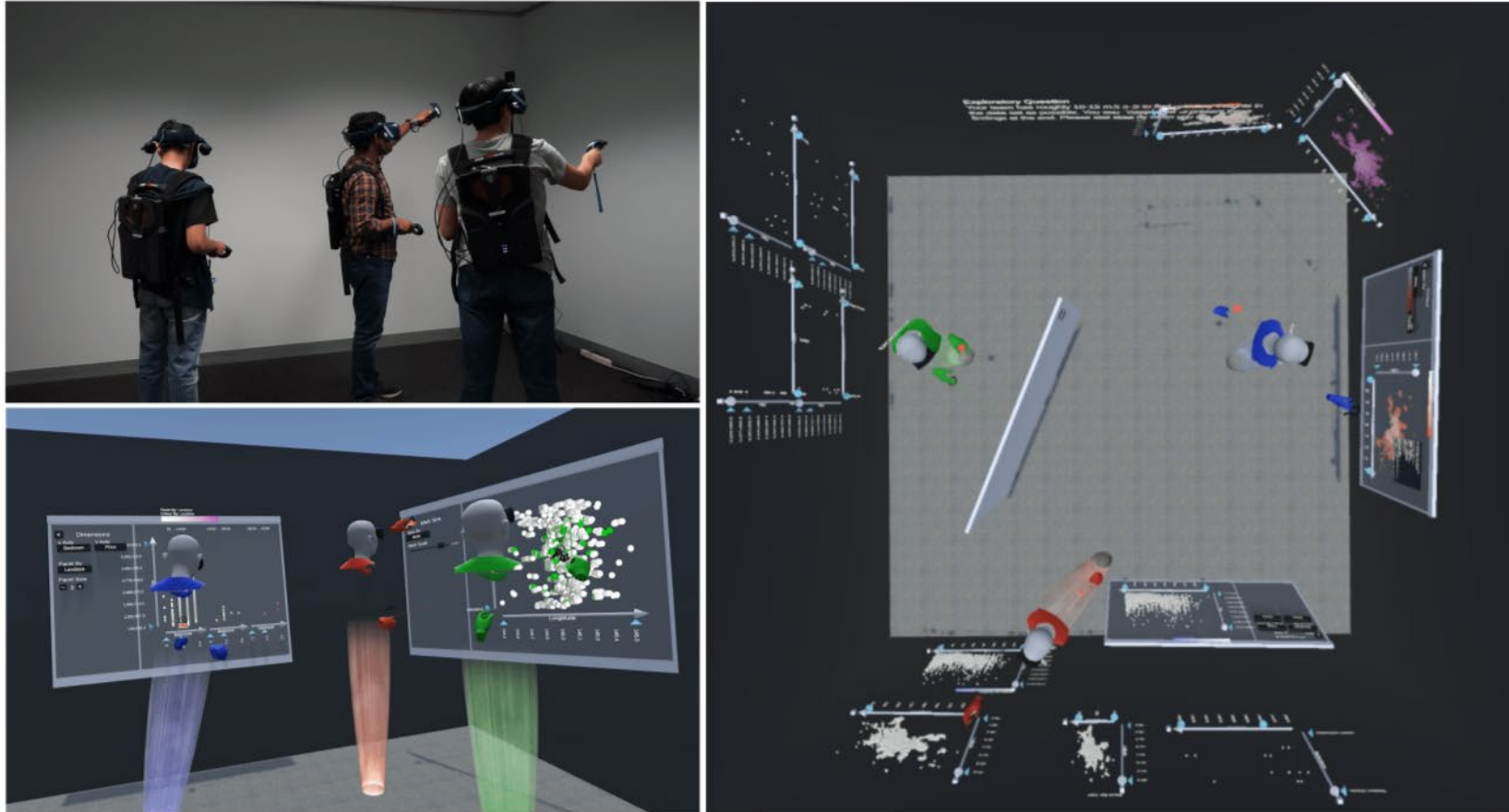
<sup>1</sup> Monash University, Australia, <sup>2</sup> University of Edinburgh, UK, <sup>3</sup> University of South Australia, Australia  
{max.cordeil,tim.dwyer}@monash.edu, bbach@ed.ac.uk,  
{andrew.cunningham, bastian.montoya, ross.smith, bruce.thomas}@unisa.edu





# Shared Surfaces and Spaces: Collaborative Data Visualisation in a Co-located Immersive Environment

Benjamin Lee, Xiaoyun Hu, Maxime Cordeil, Arnaud Prouzeau, Bernhard Jenny and Tim Dwyer



# **Shared Surfaces and Spaces: Collaborative Data Visualisation in a Co-located Immersive Environment**

Benjamin Lee, Xiaoyun Hu, Maxime Cordeil, Arnaud Prouzeau,  
Bernhard Jenny, and Tim Dwyer

Accompanying Video  
IEEE VIS 2020

# Design and Evaluation of Interactive Small Multiples Data Visualisation in Immersive Spaces

Jiazhou Liu\*

Arnaud Prouzeau<sup>†</sup>

Barrett Ens<sup>‡</sup>

Tim Dwyer<sup>§</sup>

Monash University



# Scaptics and Highlight-Planes: Immersive Interaction Techniques for Finding Occluded Features in 3D Scatterplots

**Arnaud Prouzeau**  
Monash University  
Melbourne, Australia  
arnaud.prouzeau@monash.edu

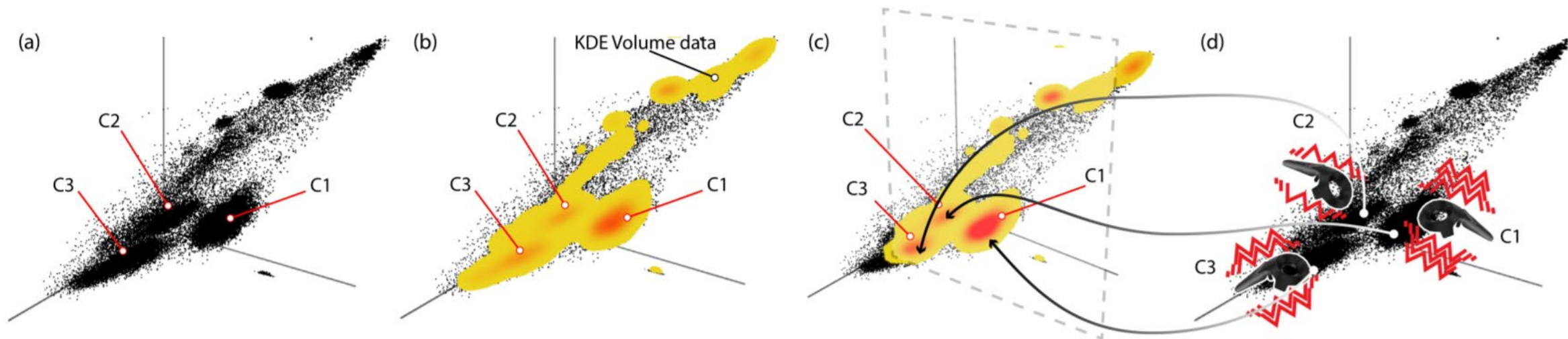
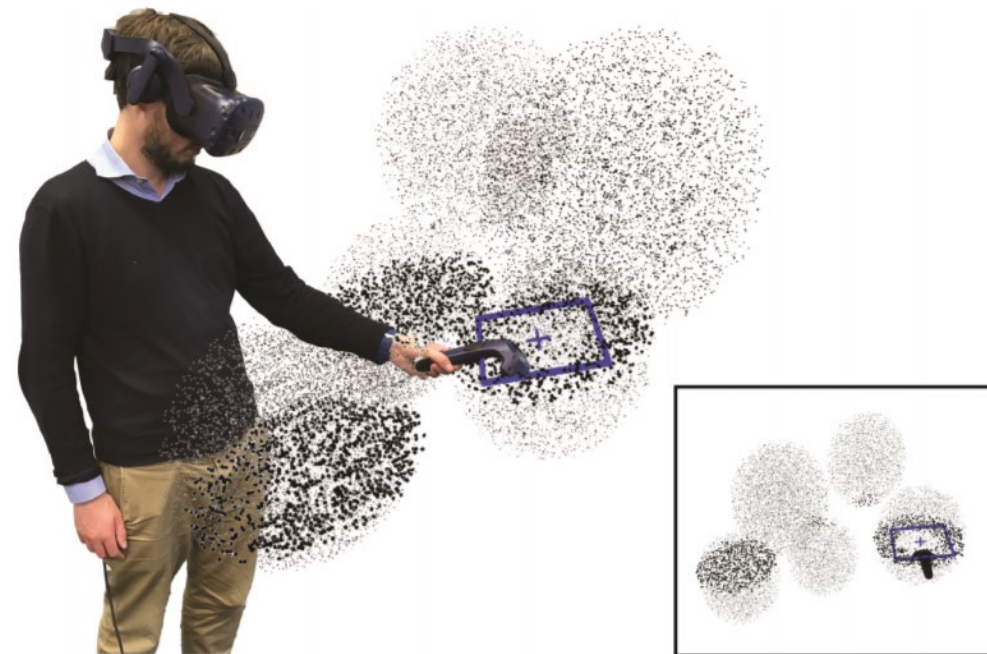
**Maxime Cordeil**  
Monash University  
Melbourne, Australia  
max.cordeil@monash.edu

**Clement Robin**  
Monash University  
Melbourne, Australia  
clement.robin09@gmail.com

**Barrett Ens**  
Monash University  
Melbourne, Australia  
barrett.ens@monash.edu

**Bruce H. Thomas**  
University of South Australia  
Adelaide, Australia  
bruce.thomas@unisa.edu.au

**Tim Dwyer**  
Monash University  
Melbourne, Australia  
tim.dwyer@monash.edu



# Take aways

- IATK scales with the number of points to visualise
  - Be considerate of the number of visualisations
- Use 3<sup>rd</sup> party Python, R, Excel to clean, order and transform your data to make them ready to visualise in IATK
- IATK is a toolkit – designed to integrate with other packages (e.g. VRTK, MapBox)
- Open source project!

Thank you



[github.com/MaximeCordeil/IATK](https://github.com/MaximeCordeil/IATK)